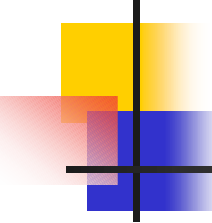




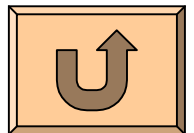
Extending Genetic Programming with Recombinative Guidance

Hitoshi Iba and
Hugo de Garis

- 
- Motivation
 - Recombinative Guidance for GP
 - **Experimental results**
 - Performance-based Guidance
 - Correlation-based Guidance for Symbolic Regression
 - MDL-based Guidance for Numerical GP
 - Discussion
 - Related Works
 - Future Works

Motivation

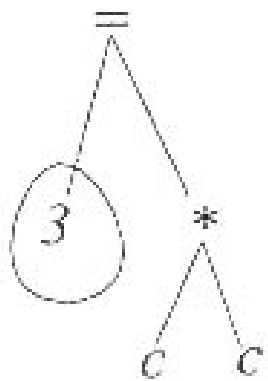
- In traditional GP, recombination causes disruption of beneficial building-blocks, and mutation causes abrupt changes in the semantics. Example.
- Propose a “recombinative guidance” mechanism for GP so as to realize an “adaptive recombination”.
- In GA
- In GP



Example

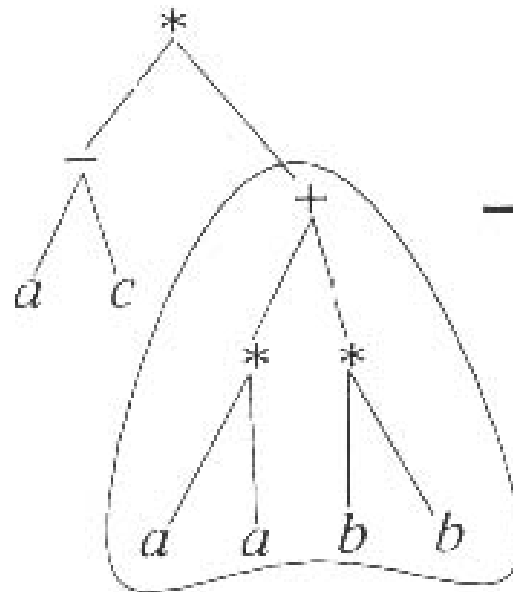
$$a^2 + b^2 = c^2$$

Parent1



+

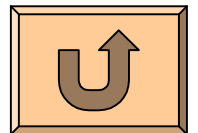
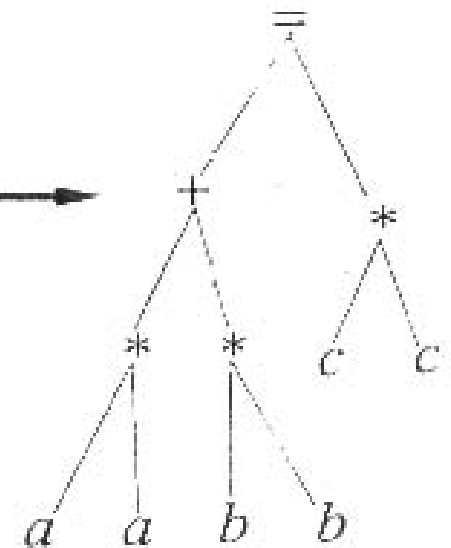
Parent2



Crossover



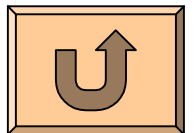
Solution Tree





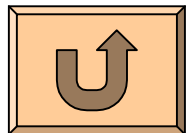
In GA

- Schaffer(1987)
 - Use a string feature called “punctuation”, which decides the crossover points of multi-point crossover.
- Back(1991, 1992, 1993)
 - Propose an adaptive control scheme for a mutation operator. Use a bit string to represent a mutation rate for each allele.



In GP

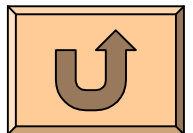
- Koza(1990, ch.4. 12.2)
 - Use a constrained crossover operator to evolve Neural Networks.
- D'haeseleer(1994)
 - The crossover operators attempt to preserve the context in which subtrees appeared in the parent tree.
- Haynes(1995)
 - Propose a strongly typed GP.
- Whigham(1995)
 - Use a context free grammar to control crossover and mutation operators for GP.





Recombinative Guidance for GP

- S-values(subtree values)
 - Denote : $SV(T)$, for a subtree T
 - Performance-based S-value
 - Correlation-based S-value
 - MDL-based S-value
- Use S-values to decide which subtree will be chosen.



S-value

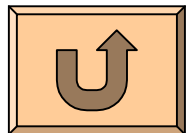
- S-values are sorted in ascending order (\overline{SV})
 - The larger S-value, the better subtree
- S-values are sorted in descending order (\underline{SV})
 - The smaller S-value, the better subtree
- For subtrees T and T' , $T \preceq T'$ denoted that T' is a better building-block candidate than T .
- If the S-value of T' is better than that of T ,

then

$$T \preceq T' \Leftrightarrow \overline{SV}(T) \leq \overline{SV}(T')$$

or

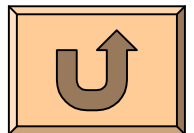
$$T \preceq T' \Leftrightarrow \underline{SV}(T) \geq \underline{SV}(T')$$





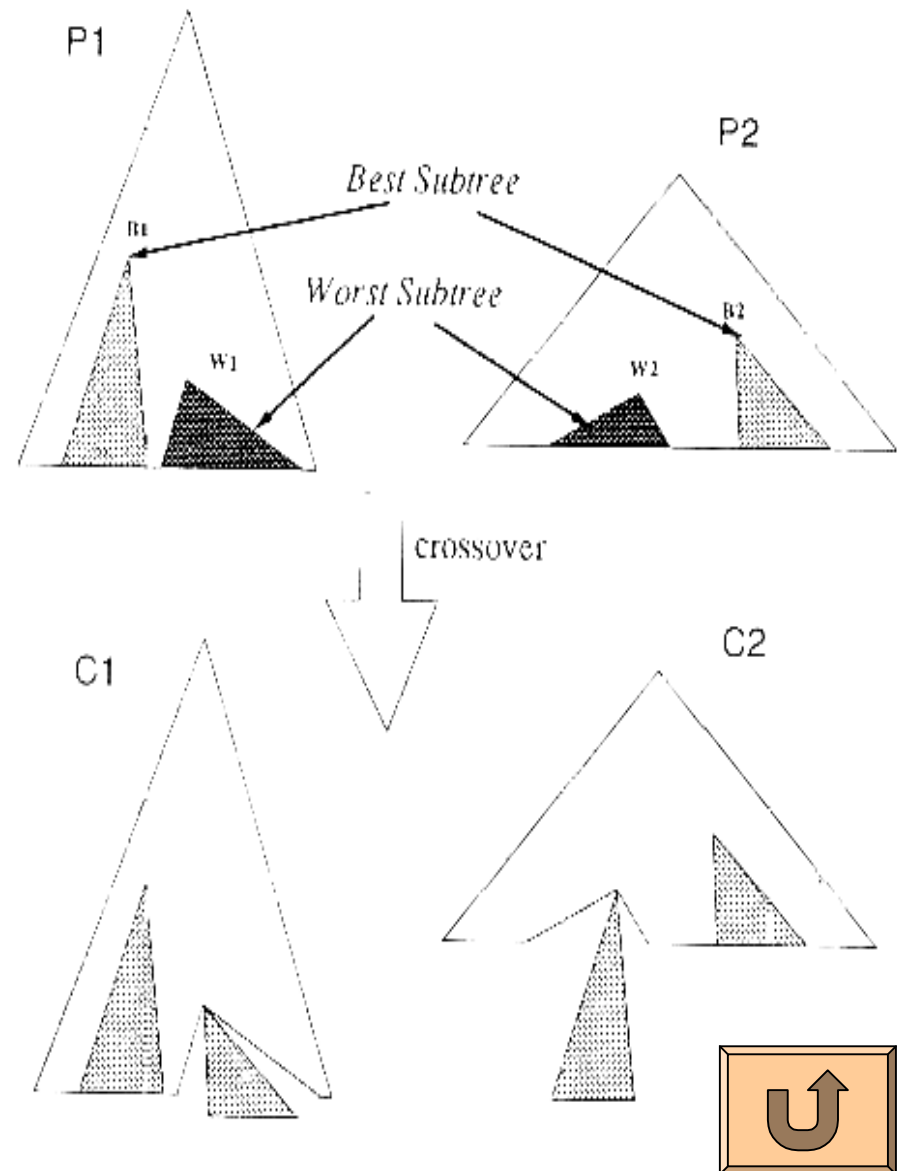
Process

- Apply a mutation operator to a subtree whose S-value is *worse*.
- Apply a crossover operator to a subtree whose S-value is *worse*, and get a subtree whose S-value is better from another parent.
- Example



Example

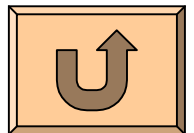
- Let W_1 and W_2 be the subtrees with the **worst** S-values of P_1 and P_2 .
- Let B_1 and B_2 be the subtrees with the **best** S-values of P_1 and P_2 .
- A new child C_1 is a copy of P_1 , in which W_1 is replaced by B_2 .
- A new child C_2 is a copy of P_2 , in which W_2 is replaced by B_1 .





Performance-based Guidance

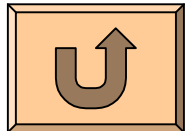
- Experiment 1
 - The Lawnmower Problem
 - (Koza 1994, ch.8)
- Experiment 2
 - Artificial Ant on the San Mateo Trail
 - (Koza 1994, ch.12)





The Lawnmower Problem

- Goal : To find a program for controlling the movement of a lawnmower so that it cuts all the grass in the yard.
- Discrete 8x8 toroidal square area
- Fitness & Termination criterion
- Parameters
- S-value
- Result





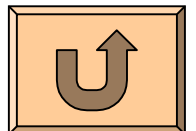
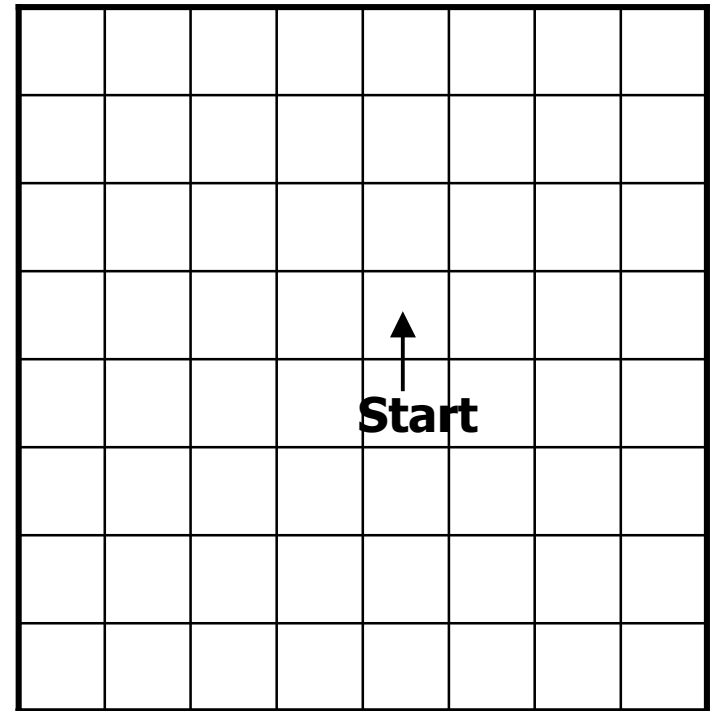
Area

- LEFT

Turn the orientation of the lawnmower counterclockwise by 90 degrees.

- MOW

Move the lawnmower in the direction it is currently facing and mows the grass.





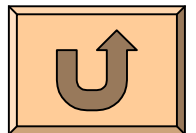
Fitness & Termination criterion

- Fitness

- Raw fitness : the amount of grass mowed
- Standard fitness : $64 - (\text{Raw fitness})$

- Termination criterion :

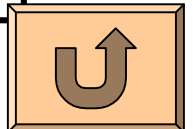
Either the lawnmower has executed a total of 100 LEFT turns or 100 MOVES.





Parameters

Terminal Set	{MOW, LEFT}
Function Set	{PROG2, PROG3}
Population Size	120
Crossover Prob.	0.7
Mutation Prob.	0.033

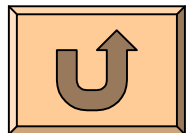




S-value

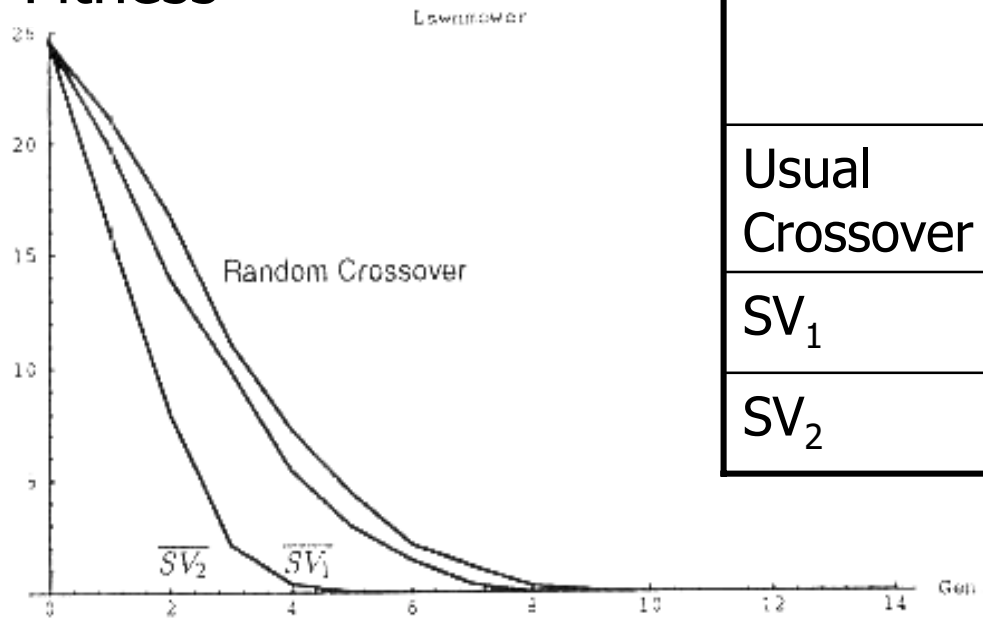
- $\overline{SV}_1(T) = \frac{\text{raw fitness}(T)}{\text{raw fitness}(\text{ROOT})}$
 - It is not defined for the root node.
 - It does not reflect the complexity of the program.
- Complexity-based S-value

$$\overline{SV}_2(T) = \frac{\text{raw fitness}(T)}{\text{raw fitness}(\text{ROOT})} + \frac{\#N(\text{ROOT}) - \#N(T)}{\#N(\text{ROOT})}$$



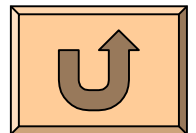
Result

Std. Fitness



Generation

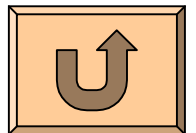
Method	Number of nodes	
	Average	Variance
Usual Crossover	603.00	95.76
SV ₁	655.53	120.27
SV ₂	496.27	50.99





Artificial Ant on the San Mateo Trail

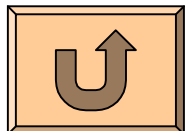
- Goal
 - To find a program for controlling the movement of an artificial ant so as to find all of the food lying along an irregular trail on a two-dimensional toroidal grid.
- Area : 13x13 grid
- Raw fitness : the sum of food pieces eaten
- Parameters & Result





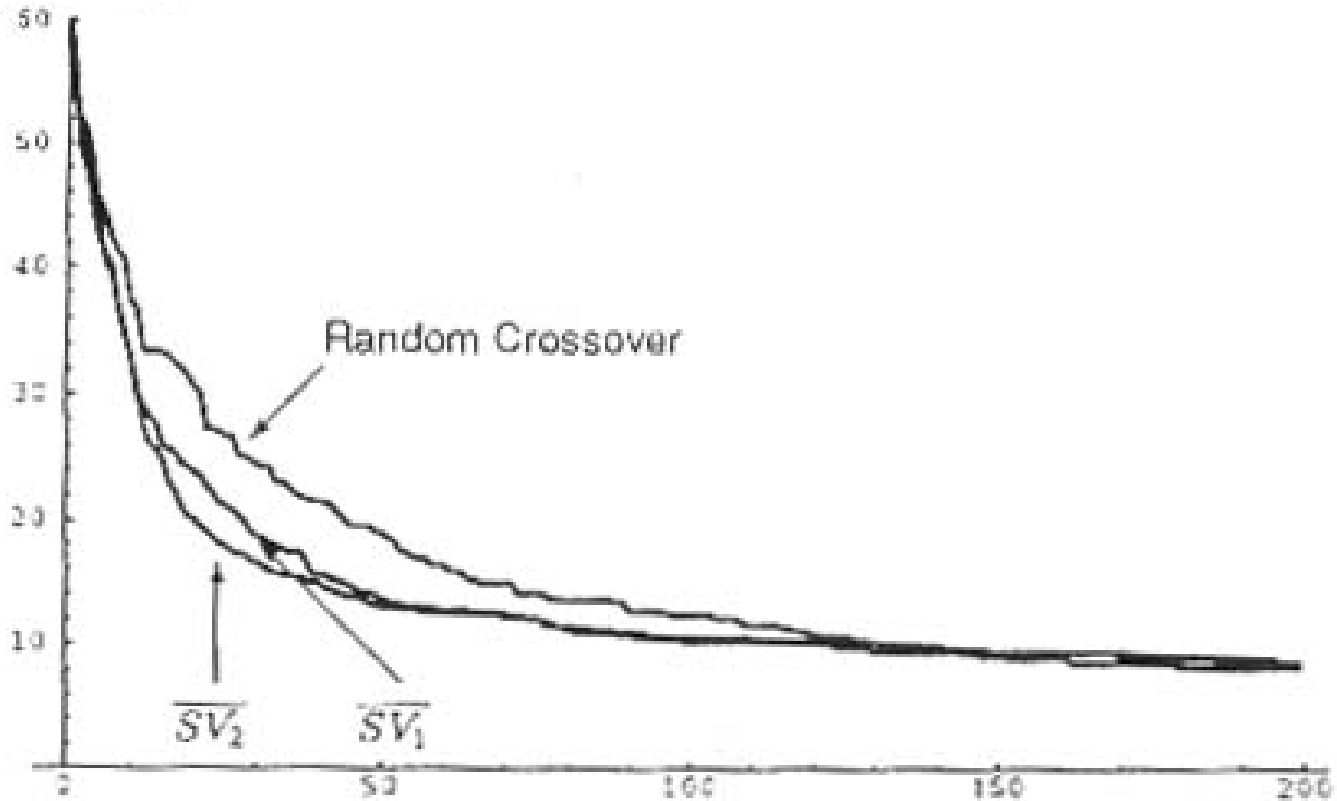
Parameters

Terminal Set	{RIGHT, LEFT, MOVE}
Function Set	{IF_FOOD_AHEAD, PROGN}
Population Size	1200
Crossover Prob.	0.7
Mutation Prob.	0.033

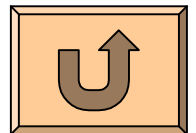


Result

Std. Fitness



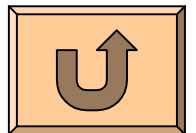
Gen.





Correlation-based Guidance for Symbolic Regression

- S-value
- Experiment 3
 - A simple symbolic regression
- Experiment 4
 - Discovery of trigonometric identities



S-value

- $\overline{SV}_3(T) = \frac{1}{N} \sum_{i=1}^N (y_i - t_i)^2$

- $\overline{SV}_4(T) = |r(T)|$

$$r(T) = \frac{S_{yT}}{\sqrt{S_{TT} \cdot S_{yy}}}$$

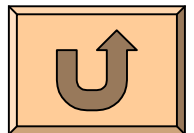
- $-1 \leq r(T) \leq 1$

- A value of $r(T)$ near zero indicates that the variable y_i and t_i are uncorrelated.

$$S_{yy} = \frac{1}{N} \sum_{i=1}^N (y_i - \bar{y})^2$$

$$S_{TT} = \frac{1}{N} \sum_{i=1}^N (t_i - \bar{t})^2$$

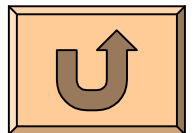
$$S_{yT} = \frac{1}{N} \sum_{i=1}^N (t_i - \bar{t})(y_i - \bar{y})$$





A simple symbolic regression

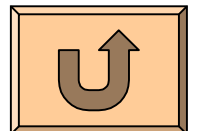
- $y = 1/2 x^2$
- Parameters
- Standard fitness vs. Generation
- Average Number of Success Generations
(the number of success for 20 runs within a maximum of 200 generations)





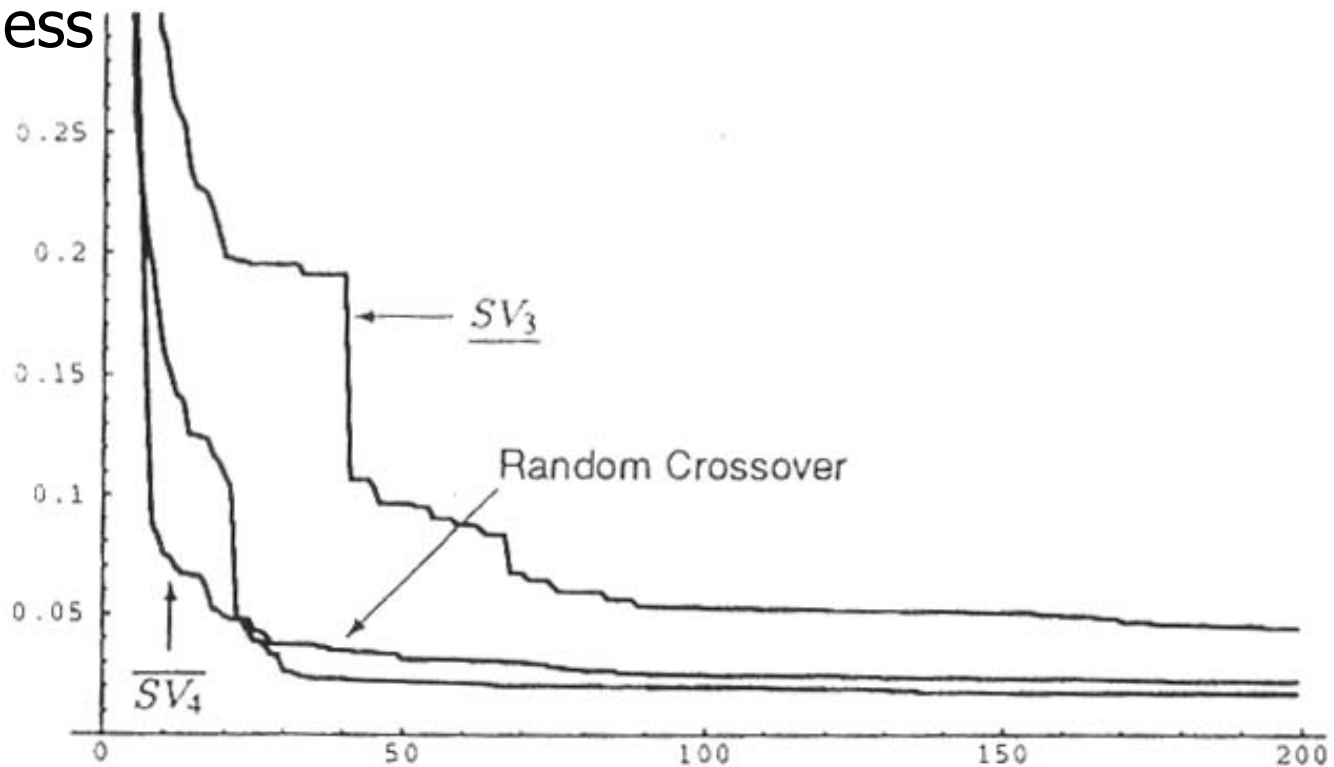
Parameters

# of Fitness Cases	20
Terminal Set	{X}
Function Set	{+, -, ×, ÷}
Population Size	40
Crossover Prob.	0.7
Mutation Prob.	0.033
Generation	200

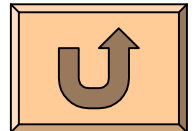


Standard fitness vs. Generation

Std. Fitness

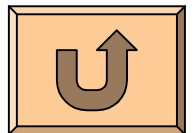


Gen.



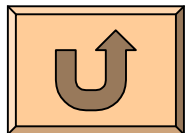
Average Number of Success Generations

Method	# of Success	Average Gen.
Usual Recombination	10	18.88
SV ₃	9	25.5
SV ₄	14	5.93



Discovery of trigonometric identities

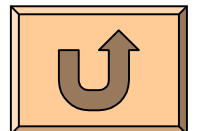
- $\cos^2 x = 1 - \sin^2 x$
 - 20 pairs (x_i, y_i) , $x_i \in [0, 2\pi]$
- Parameters
- Std. Fitness vs. Gen.



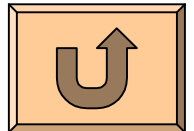
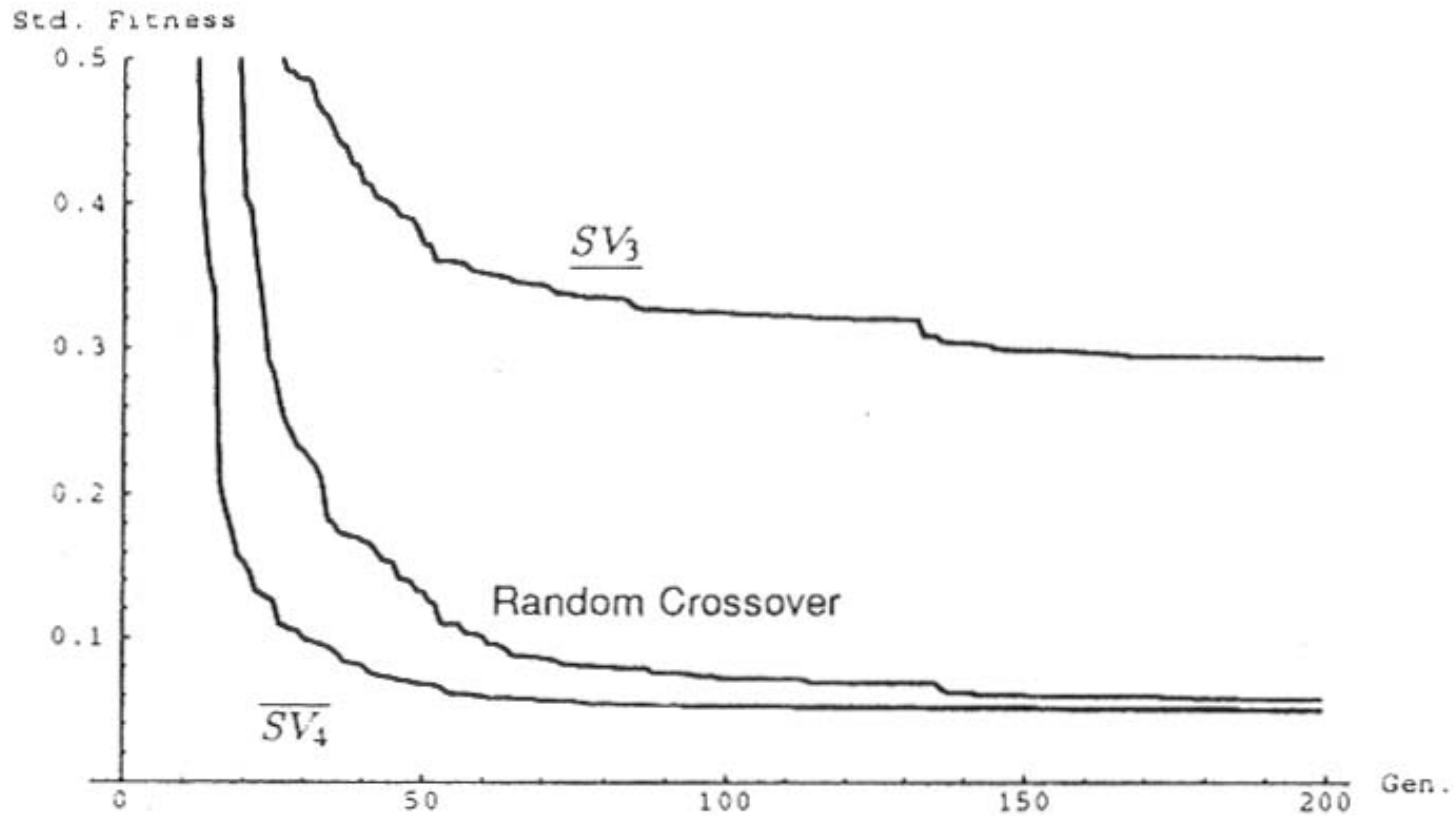


Parameters

# of Fitness Cases	20
Terminal Set	{x, 1.0}
Function Set	{+, -, ×, ÷, sin}
Population Size	500
Crossover Prob.	0.7
Mutation Prob.	0.033

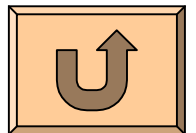


Std. Fitness vs. Gen.



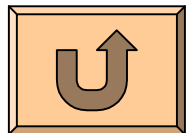
MDL-based Guidance for Numerical GP

- Advantages of STROGANOFF
- MDL fitness definition
- Chose the MDL value as the S-value for each subtree T : $\underline{SV}_{MDL}(T) = MDL(T)$
- Predict the Mackey-Glass time series
- STROGANOFF parameters
- Results



Advantages of STROGANOFF

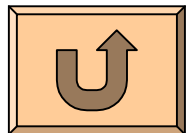
- Analog(polynomial) expressions complemented the digital(symbolic) semantics. The representational problem of standard GP does not arise for STROGANOFF.
- MDL-based fitness evaluation works well for tree structures in STROGANOFF, which controls GP-based tree search.
- Multiple-regressions tuned the node coefficients so as to guide GP recombination effectively.





MDL fitness definition

- $MDL = 0.5N \log S_N^2 + 0.5k \log N$
 - N : the number of data pairs
 - S_N^2 : the mean square error
 - $S_N^2 = \frac{1}{N} \sum_{i=1}^N |\bar{y}_i - y_i|^2$
 - k : the number of parameters of the tree

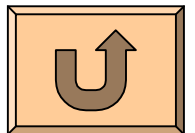




The Mackey-Glass time series

$$\frac{dx(t)}{dt} = \frac{ax(t-\tau)}{1+x^{10}(t-\tau)} - bx(t)$$

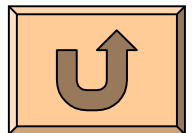
- $a=0.2$, $b=0.1$ and $\tau=17$
- The trajectory is chaotic and lies on an approximately 2.1 dimensional strange attractor.



STROGANOFF parameters

Population Size	120
Prob. of Crossover	60%
Prob. of Mutation	3.3%
Selection Method	Tournament
Non-terminal Nodes	$\{a_0 + a_1x_1 + a_2x_2 + a_3x_1x_2 + a_4x_1^2 + a_5x_2^2\}$
Terminal Nodes	$\{x(t), x(t-6), x(t-12), x(t-18)\}$
Target Variable	$x(t+85)$
# of Training Data	500
# of Testing Data	500

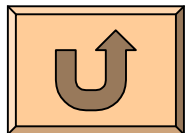
Following Hartman(1991)



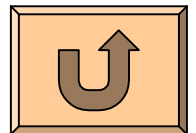
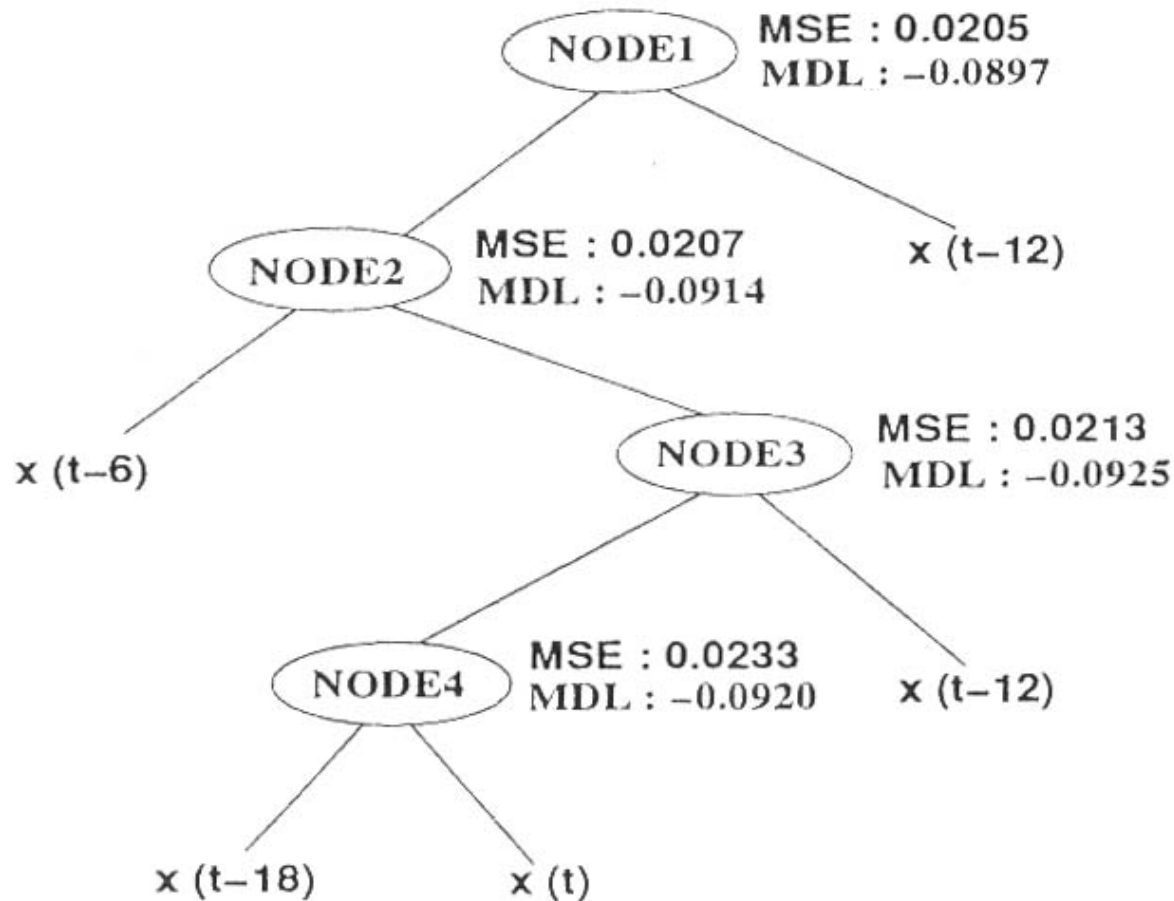


Results (MDL-based)

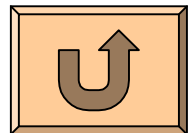
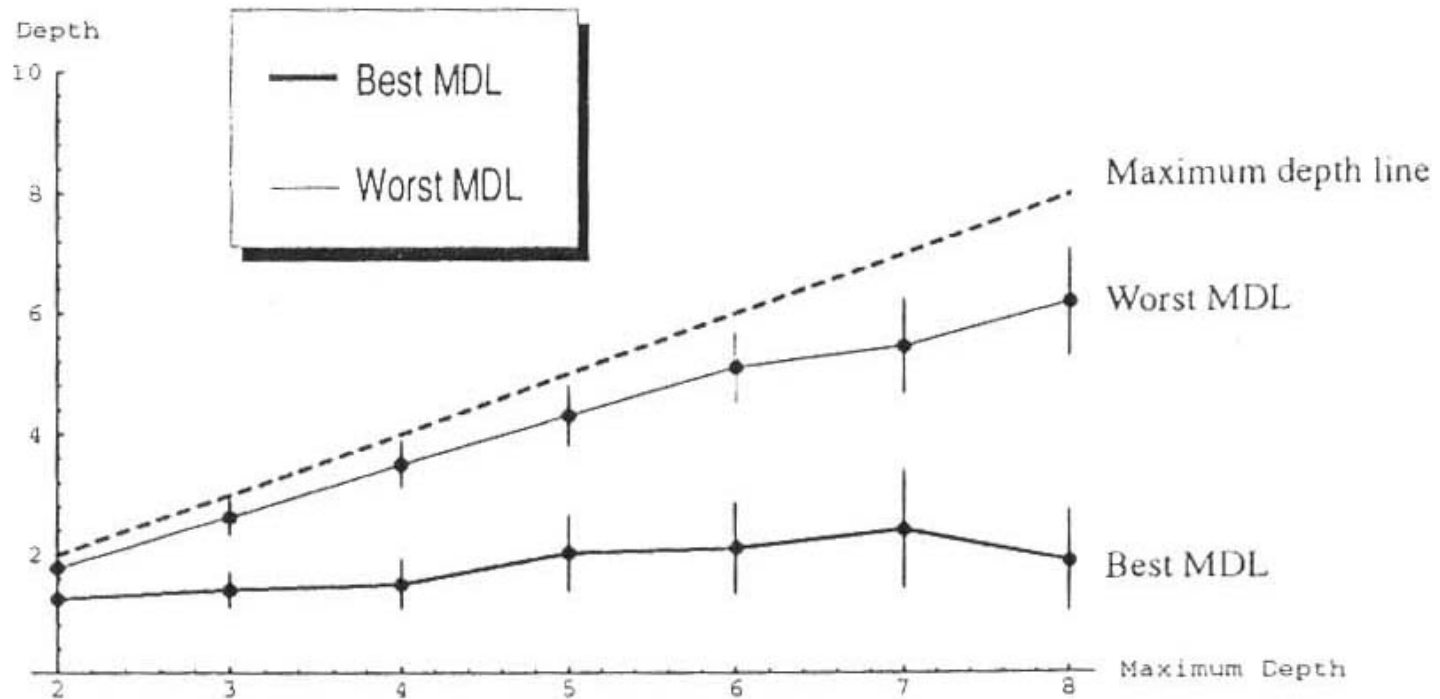
- An Exemplar Tree
- Average Depths of Node of Best and Worst MDL values
- Prediction of Mackey-Glass Equation



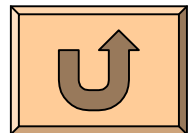
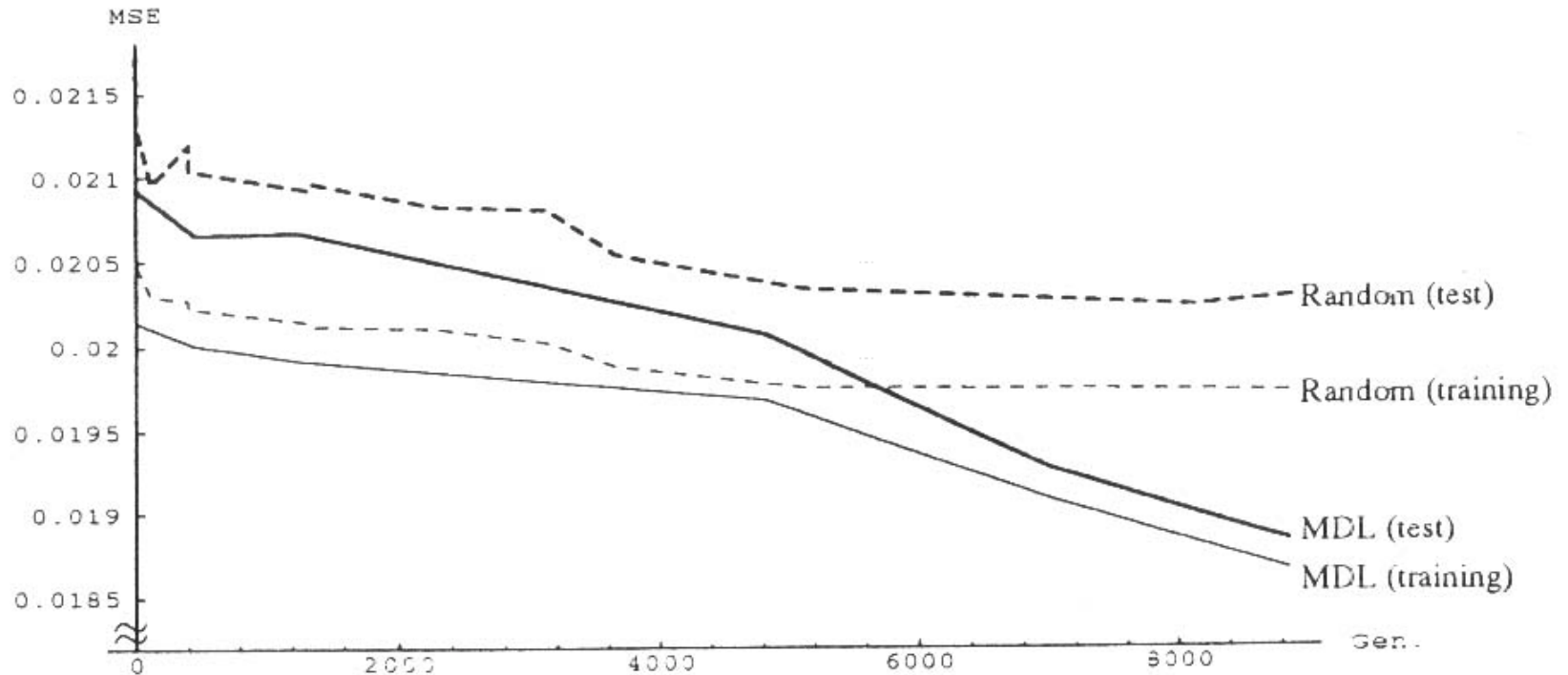
An Exemplar Tree



Average Depths of Node of Best and Worst MDL values

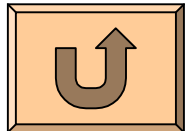


Prediction of Mackey-Glass Equation



Discussion

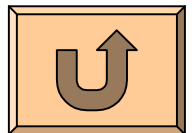
Problem	Reference	Result
Lawnmower	Koza 1994, ch.8	$R \preceq \overline{SV}_1 \preceq \overline{SV}_2$
Ant Trail	Koza 1994, ch.12	$R \preceq \overline{SV}_1 \preceq \overline{SV}_2$
Regression 1	Koza 1992, p.163	$\underline{\underline{SV}}_3 \preceq R \preceq \underline{\underline{SV}}_4$
Regression 2	Koza 1992, ch.10.1	$SV_3 \preceq R \preceq \overline{SV}_4$
Time Series Pred.	Iba 1993, 1994	$R \preceq \underline{\underline{SV}}_{MDL}$





The Success of methods

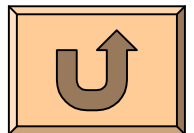
- Although there is no theoretical background for SV_2 definition, SV_2 is similar to MDL-based evaluation.
 - We may regard the first term of SV_2 as the inverse of the Exception_Coding_Length and the second term as the inverse of the Tree_Coding_Length.
- SV_2 and \underline{SV}_{MDL} evaluate the trade-off between performance and tree descriptions.





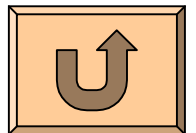
The Success of methods

- The MSE gives very little information as to whether a building-block will be useful.
- But, a correlation coefficient is a rather poor statistic for deciding whether an observed correlation is statistically significant.
- SV_4 is introduced as a way to evaluate the S-value heuristically, not as an absolute index.



Related Works

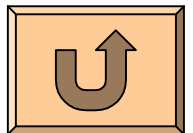
- Rosca (1994)
 - Use Block fitness function to discover a useful building block by his system AR-GP.
- Angeline (1996)
 - Selective self-adaptive crossover and self-adaptive multi-crossover.
- Tackett (1995a)
 - Greedy Recombination operator.
- Teller (1996)
 - The co-evolution of intelligent recombination operators.
- Nordin (1996)
 - The introns regulate the crossover probabilities for subtrees.





Future Works

- Is it possible to design effective S-values for various problems?
- The approach can be combined with ADF.
- Formalize S-values in more mathematical ways.
- Eliminate the constraint of the “linear order” for the S-values.





Formalize S-values

- A characteristic of S-values : if a subtree is a good building-block, it has a good S-value. That is

$$T \leq T' \iff \text{Pr ob}(T) < \text{Pr ob}(T')$$

Where $\text{Prob}(T)$ is the probability that a subtree T is part of a solution tree.

