## STATISTICAL ANALYSIS OF GENETIC ALGORITHMS IN DISCOVERING TECHNICAL TRADING STRATEGIES

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#### Abstract

In this study, the performance of ordinal GA-based trading strategies is evaluated under six classes of time series model, namely, the linear ARMA model, the bilinear model, the ARCH model, the GARCH model, the threshold model and the chaotic model. The performance criteria employed are the winning probability, accumulated returns, Sharpe ratio and luck coefficient. Asymptotic test statistics for these criteria are derived. The hypothesis as to the superiority of GA over a benchmark, say, buy-and-hold, can then be tested using Monte Carlo simulation. From this rigorouslyestablished evaluation process, we find that simple genetic algorithms can work very well in linear stochastic environments, and that they also work very well in nonlinear deterministic (chaotic) environments. However, they may perform much worse in pure nonlinear stochastic cases. These results shed light on the superior performance of GA when it is applied to the two tick-by-tick time series of foreign exchange rates: EUR/USD and USD/JPY.


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## 1. INTRODUCTION

Genetic algorithms (GAs) have been developed by Holland (1975) to mimic some of the processes observed in natural evolution. They are based on the genetic processes of natural selection which have become widely known as the "survival of the fittest" since Darwin's celebrated work. In recent years, GAs have been successfully applied to find good solutions to real-world problems whose search space is complex, such as the traveling salesman problem, the knapsack problem, large scheduling problems, graph partitioning problems, and engineering problems, too. ${ }^{1}$

In finance, Bauer (1994) provides the first application of GAs to discover trading strategies. Since then, GAs have gradually become a standard tool for enhancing investment decisions. ${ }^{2}$ While many studies have supported the effectiveness of GAs in investment decisions; however, the foundation of these applications has not been well established. The thing that concerns us, therefore, is the robustness of these empirical results. For example, if GAs are effective for the investment in one market at one time, would the same result apply to the same market or different markets at different times? It is for the purpose of pursuing this generality, that we see the necessity of building a solid foundation upon which a rigorous evaluation can be made.

In this paper, a statistical approach to testing the performance of GA-based trading strategies is proposed. Instead of testing the performance of GAs in specific markets as a number of conventional studies already have, we are interested in a market-independence issue: what makes GAs successful and what makes them not? Since the data to which GAs are applied consist of financial time series, the question can be rephrased as follows: what are the statistical properties which distinguish a successful application of GA from an unsuccessful one? One way to think of the question is to consider two markets following different stochastic processes. One market follows stochastic process A, and the other stochastic process B. If GAs can work well with stochastic process $A$, but not $B$, then the successful experience of GAs in the first market is certainly not anticipated in the second market.

Having said that, this paper follows the following research methodology. First, some financially-related stochastic processes are singled out as the standard scenarios (testbeds) to test the performance of GA. Second, appropriate performance criteria are used to evaluate the performance of the GA over these testbeds. Third, the associated asymptotic statistical tests are applied to examine whether the GAs perform significantly differently as opposed to a familiar benchmark. By this procedure, we may be able to distinguish the processes in which the GA has competence from others in which it does not. Once the critical properties are grasped, we can then apply the GA to the financial time series whose
stochastic properties are well-known, and test whether the GA behaves consistently with what we have learned from the previous statistical analysis.

By means of the procedure established in this paper, we hope to push forward the current applications of GAs or, more generally, computational intelligence (CI), toward a more mature status. After all, whether GA will work has been asked too intensely in the literature. The very mixed results seem to suggest that we look at the same question at a finer level and start to inquire why it works or why it doesn't. We believe that there are other ways to do something similar to what we propose in this paper. ${ }^{3}$ We do not exclude these possibilities. In fact, little by little, these efforts will eventually enable GA or CI tools to rid themselves of their notoriety for being blackboxes.

The rest of the paper is organized as follows. Section 2 introduces a specific version of GA, referred as to the ordinary GA (OGA), used in this paper. Section 3 will detail the classes of stochastic processes considered in this paper and the reasons for this choice. Section 4 reviews the four performance criteria and establishes their associated asymptotic test. Section 5 sets up the Monte Carlo simulation procedure. Section 6 summarizes and discusses the actual performance of the GA over the artificial data, whereas the counterpart over the real data is given in Section 7. Section 8 concludes this paper.

## 2. TRADING WITH GAS

A trading strategy $g$ can be formally defined as a mapping:

$$
\begin{equation*}
g: \Omega \rightarrow\{0,1\} . \tag{1}
\end{equation*}
$$

In this paper, is assumed to be a collection of finite-length binary strings. This simplification can be justified by the data-preprocessing procedure which transforms the raw data into binary strings. The range of the mapping $g$ is simplified as a $0-1$ action space. In terms of simple market-timing strategy, " 1 " means to "act" and " 0 " means to "wait." Here, for simplicity, we are only interested in day trading. So, "act" means to buy it at the opening time and sell it at the closing time.

Like all financial applications of GA, the start-off question is the representation issue. In our case, it is about how to effectively characterize the mapping $g$ by a finite-length binary string, also known as a chromosome in GA. Research on this issue is very much motivated by the format of existing trading strategies, and there are generally two approaches to this issue. The first approach, called the decision tree approach, was pioneered by Bauer (1994). In this approach each trading strategy is represented by a decision tree. Bauer used bit strings to encode these decision tress, and generated and evolved them with genetic algorithms. The
second approach, called the combinatoric approach, was first seen in Palmer et al. (1994). The combinatoric approach treats each trading strategy as one realization from $\binom{n}{k}$ combinations, where $l \leq k \leq n$, and $n$ is the total number of given trading rules. Using GAs, one can encode the inclusion or exclusion of a specific trading rule as a bit and the whole trading strategy as a bit string (chromosome).

Both approaches have very limited expression power. While various enhancements are possible, they all lead to non-standard GAs in the sense that their representations are not based on finite-length binary strings. Since the main focus of this paper is to illustrate a statistical foundation of the GA, we try to avoid all unnecessary complications, including the use of those non-standard representations. In other words, at this initial stage, we only make the illustration with the ordinary genetic algorithm (OGA), and, for that reason, Bauer's simple decision- tree representation is employed. However, it is clear that the statistical foundation presented in this paper is also applicable to GAs with different representations.

Bauer's decision-tree representation corresponds to the following general form of trading strategies

## (IF (CONDS) <br> THEN (BUY AND SELL [DAY TRADING]) <br> ELSE (WAIT)).

The CONDS appearing in the trading strategy is a predicate. CONDS itself is a logical composition of several primitive predicates. In this paper, all CONDSs are composed of three primitive predicates. Each primitive predicate can be represented as:

$$
\operatorname{Cond}(Z)= \begin{cases}1(\text { True }), & \text { if } Z \oplus a  \tag{2}\\ 0(\text { False }), & \text { if } Z \oplus a\end{cases}
$$

where $Z$, in our application, can be considered as a time series of returns indexed by $t$, e.g. $r_{t-1}, r_{\mathrm{t}-2}$, etc., and $a$ can be regarded as a threshold or critical value ( $a \in \aleph$, a set of integers). $\oplus \in\{\geq,<\}$ and $\Theta=\{\geq,<\}-\oplus$. An example of CONDS with three primitive predicates is

$$
\begin{equation*}
\operatorname{CONDS}\left(r_{t-1}, r_{t-2}, r_{t-3}\right)=\operatorname{Cond}\left(r_{t-1}\right) \vee\left(\operatorname{Cond}\left(r_{t-2}\right) \wedge \operatorname{Cond}\left(r_{t-3}\right)\right) \tag{3}
\end{equation*}
$$

where " $\vee$ " refers to the logic operator "OR," and " $\wedge$ " refers to "AND."
Following Bauer, we use a 21-bit string to encode a trading strategy of this kind. Details can be found in the Appendix (Section A.1). Let $G$ be the collection of all trading strategies encoded as above. Then the cardinality of $G$ is $2^{21}$
$\left(\#(G)=2^{21}\right)$, which is more than 2 million. The search over the space $G$ can be interpreted as a numerical algorithm as well as a machine learning algorithm for solving a mathematical optimization problem. Without losing generality, consider the trading strategy with only one primitive predicate,

$$
\operatorname{Cond}(Z)= \begin{cases}1 \text { (True) }, & \text { if } r_{t-1} \geq a,  \tag{4}\\ 0(\text { False }), & \text { if } r_{t-1}<a\end{cases}
$$

Suppose the stochastic process of $r_{t}$ is strictly stationary and denote the joint density of $r_{t-1}$ and $r_{t}$ by $f\left(r_{t-1}, r_{t}\right)$. In this simplest case, a trading strategy is parameterized by a single parameter $a$. Denote it by $g_{a}$. Then the optimal strategy $g_{a^{*}}$ can be regarded as a solution to the optimization problem

$$
\begin{equation*}
\max _{a} E\left(\ln \left(\pi_{n}\right)\right), \tag{5}
\end{equation*}
$$

where

$$
\begin{equation*}
\pi_{n}=\prod_{t=1}^{n}\left(1+r_{t}\right) \tag{6}
\end{equation*}
$$

is the accumulated returns of $g_{a}$ over $n$ consecutive periods. It can be shown that the solution to the problem (5) is

$$
\begin{equation*}
a^{*}=F^{-1}(0), \quad \text { if } F^{-1}(0) \text { exists. } \tag{7}
\end{equation*}
$$

where

$$
\begin{equation*}
F(a)=\int_{-\infty}^{\infty} \ln \left(1+r_{t}\right) f\left(a, r_{t}\right) \mathrm{dr}_{t} \tag{8}
\end{equation*}
$$

To solve Eq. (7), one has to know the density function of $f\left(r_{t-1}, r_{t}\right)$, which can only be inferred from the historical data. In this case, GAs are used as a machine learning tool to obtain an estimate of this joint density. Also, to arrive at a value for $a^{*}$, we have to know the inverse function of $F(a)$, which in general can only be solved numerically. In this case, GAs are used as a numerical technique to solve this problem. Therefore, in the trading-strategy problem, GAs are used simultaneously as a numerical technique and a machine learning tool to determine the critical parameter $a^{*}$. In the general case when CONDS has more than one predicate, the mathematical formulation of the problem can become very complicated, but the dual role of GAs remains unchanged. This interpretation justifies the mathematical significance of using GAs to discover the trading strategies.

The GA employed in this paper is a very basic version, which we shall call the ordinary genetic algorithm (OGA). In this study, we only focus on the OGA. Nonetheless, in a further study, it will be interesting to see whether a better result
can be expected from advanced versions of GAs. The technical details of the OGA are given in the Appendix (Section A.2).

## 3. TESTBEDS

There are six stochastic processes used to evaluate the performance of GAs. They are:
(1) the linear stationary time series (also known as the Auto-Regressive and Moving-Average (ARMA) processes),
(2) the bilinear processes,
(3) the Auto-Regressive Conditional Heteroskedasticity (ARCH) processes,
(4) the Generalized ARCH (GARCH) processes,
(5) the threshold bilinear processes, and
(6) the chaotic processes.

All of the six classes have been frequently applied to modeling financial time series. Linear ARMA processes are found to be quite useful in high-frequency financial data (Campbell et al., 1997; Roll, 1984). Bilinear processes are often used to model the nonlinear dependence in both low- and high-frequency data (Drunat et al., 1998; Granger \& Andersen, 1978). The ARCH processes are the most popular econometric tools for capturing the nonlinear dependence in the form of the second moment (Bollerslev et al., 1992). The threshold processes are good for asymmetric series and bursts (Tong, 1990). Finally, chaotic time series have been a topic of interest in finance over the last decade (Brock et al., 1991). Some details of these classes of processes are briefly reviewed from Sections 3.1 to 3.6.

These six processes are general enough to cover three important classes of dynamic processes, namely, linear stochastic processes, nonlinear stochastic processes, and nonlinear deterministic processes. This enables us to analyze the GA's performance in terms of some generic properties. For example, would it be easier for the GA to perform better with the linear (stochastic) process than with the nonlinear (stochastic) process, and with the deterministic (nonlinear) processes than with the stochastic (nonlinear) processes? The answers to these questions can certainly help us to delineate the effectiveness of GAs.

### 3.1. Linear Time Series

The linear time series model, also known as the Auto-Regressive and MovingAverage $(\operatorname{ARMA}(p, q))$ model, was initiated by Box and Jenkings (1976). It has the

Table 1. Data Generating Processes - ARMA

| Code | Model | Parameters |  |  |  |
| :--- | :--- | :--- | :---: | :---: | ---: |
|  |  | $\phi_{1}$ | $\phi_{2}$ | $\theta_{1}$ | $\theta_{2}$ |
| L-1 | ARMA(1,0) | 0.3 | 0 | 0 | 0 |
| L-2 | ARMA(1,0) | 0.6 | 0 | 0 | 0 |
| L-3 | ARMA(2,0) | 0.3 | -0.6 | 0 | 0 |
| L-4 | ARMA(2,0) | 0.6 | -0.3 | 0 | 0 |
| L-5 | ARMA(0,1) | 0 | 0 | 0.3 | 0 |
| L-6 | ARMA(0,1) | 0 | 0 | 0.6 | 0 |
| L-7 | ARMA(0,2) | 0 | 0 | 0.3 | -0.6 |
| L-8 | ARMA(0,2) | 0 | 0 | 0.6 | -0.3 |
| L-9 | ARMA(1,1) | 0.3 | 0 | -0.6 | 0 |
| L-10 | ARMA(1,1) | 0.6 | 0 | -0.3 | 0 |
| L-11 | ARMA(2,2) | 0.4 | -0.4 | 0.4 | 0.4 |
| L-12 | ARMA(2,2) | 0.6 | -0.3 | -0.3 | -0.6 |
| L-13 | White Noise |  | Gaussian $(0,0.1)$ |  |  |

following general form:

$$
\begin{equation*}
r_{t}=\mu+\sum_{i=1}^{p} \phi_{i} r_{t-i}+\sum_{j=1}^{q} \theta_{j} \varepsilon_{t-j}+\varepsilon_{t} \tag{9}
\end{equation*}
$$

where $\varepsilon_{t} \stackrel{i i d}{\sim} N\left(0, \sigma^{2}\right)$. In all Monte Carlo simulations conducted in this paper, $\mu$ is set to 0 and $\sigma^{2}$ is set to 0.01 . Thirteen $\operatorname{ARMA}(p, q)$ models were tested. The parameters of these thirteen $\operatorname{ARMA}(p, q)$ models are detailed in Table 1. Among these thirteen models, there are four pure AR models (L1-L4), four pure MA models (L5-L8), and four mixtures (L9-L12). The last one is simply Gaussian white noise.

### 3.2. Bilinear Process

The second class of stochastic processes considered in this paper is the bilinear process (BL), which was first studied by Granger and Anderson (1978), and subsequently by Subba-Rao (1981) and Subba-Rao and Gabr (1980). The BL process is constructed simply by adding the cross-product terms of $r_{t-i}$ and $\varepsilon_{t-j}$ to a linear ARMA process so it can be regarded as a second-order nonlinear time series model. In other words, if the parameters of all cross-product terms are zero, then the BL process can be reduced to the ARMA process.

Table 2. Data Generating Processes - Bilinear.

| Code | Model | Parameters |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | $\phi_{1}$ | $\theta_{1}$ | $\psi_{11}$ | $\psi_{12}$ | $\psi_{21}$ | $\psi_{22}$ |
| BL-1 | BL $(0,0,1,1)$ | 0 | 0 | 0.6 | 0 | 0 | 0 |
| BL-2 | BL(0,0,1,1) | 0 | 0 | 0.3 | 0 | 0 | 0 |
| BL-3 | BL(0,1,1,2) | 0 | 0.3 | 0 | 0.6 | 0 | 0 |
| BL-4 | BL(0,1,1,2) | 0 | 0.6 | 0 | 0.3 | 0 | 0 |
| BL-5 | BL $(1,0,2,1)$ | 0.3 | 0 | 0 | 0 | 0.6 | 0 |
| BL-6 | BL $(1,0,2,1)$ | 0.6 | 0 | 0 | 0 | 0.3 | 0 |
| BL-7 | BL $(1,1,2,2)$ | 0.3 | 0.3 | 0 | 0 | 0 | 0.3 |
| BL-8 | BL(1,1,2,2) | 0.3 | 0.3 | 0 | 0 | 0 | 0.6 |

The general form of a bilinear process, $\operatorname{BL}(p, q, u, v)$ is:

$$
\begin{equation*}
r_{t}=\mu+\sum_{i=1}^{p} \phi_{i} r_{t-i}+\sum_{j=1}^{q} \theta_{j} \varepsilon_{t-j}+\sum_{m=1}^{u} \sum_{n=1}^{v} \psi_{m n} r_{t-m} \varepsilon_{t-n}+\varepsilon_{t}, \tag{10}
\end{equation*}
$$

where $\varepsilon_{t} \stackrel{i i d}{\sim} N\left(0, \sigma^{2}\right)$. Eight specific bilinear processes are employed for our MonteCarlo simulation. In all of these processes, $\mu=0$ and $\sigma^{2}=0.01$. Other parameters are given in Table 2. Notice that the first two (BL-1, BL-2) do not have the linear component, and only the nonlinear cross-product terms are presented.

### 3.3. ARCH Processes

The third class of models considered is the Auto-Regressive Conditional Heteroskedasticity (ARCH) process introduced by Engle (1982), which has played a dominant role in the field of financial econometrics. The ARCH process is mainly used to replicate the three stylized facts of financial time series, namely, the fattailed marginal distribution of returns, the time-variant volatility of the returns, and clustering outliers. Consequently, unlike the ARMA process, ARCH mainly works only on the second moment, rather than the first moment. Nonetheless, by combining the two, one can attach an $\operatorname{ARMA}(p, q)$ process with an $\operatorname{ARCH}\left(q^{\prime}\right)$ process, called the $\operatorname{ARMA}(p, q)-\operatorname{ARCH}\left(q^{\prime}\right)$ process. Its general form is

$$
\begin{align*}
& r_{t}=\mu+\sum_{i=1}^{p} \phi_{i} r_{t-i}+\sum_{j=1}^{q} \theta_{j} \varepsilon_{t-j}+\varepsilon_{t}  \tag{11}\\
& \varepsilon_{t} \mid \Omega_{t-1} \sim N\left(0, \sigma_{t}^{2}\right) \tag{12}
\end{align*}
$$

Table 3. Data Generating Processes - ARCH.

| Code | Model | Parameters |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | ---: |
|  |  | $\omega$ | $\alpha_{1}$ | $\alpha_{2}$ | $\phi_{1}$ | $\theta_{1}$ |
| AH-1 | AR(0)-ARCH(1) | 0.005 | 0.3 | 0 | 0 | 0 |
| AH-2 | AR(0)-ARCH(1) | 0.005 | 0.6 | 0 | 0 | 0 |
| AH-3 | AR(0)-ARCH(2) | 0.001 | 0.3 | 0.5 | 0 | 0 |
| AH-4 | AR(0)-ARCH(2) | 0.001 | 0.5 | 0.3 | 0 | 0 |
| AH-5 | AR(1)-ARCH(1) | 0.005 | 0.6 | 0 | 0.6 | 0 |
| AH-6 | AR(1)-ARCH(2) | 0.001 | 0.5 | 0.3 | 0.6 | 0 |
| AH-7 | MA(1)-ARCH(1) | 0.005 | 0.3 | 0 | 0 | -0.6 |

$$
\begin{equation*}
\sigma_{t}^{2}=\omega+\sum_{m=1}^{q^{\prime}} \alpha_{m} \varepsilon_{t-m}^{2} \tag{13}
\end{equation*}
$$

where $\omega>0, \sigma_{m} \geq 0, m=1, \ldots, q^{\prime}$ and $\Omega_{t}$ denotes the information set available at time $t$.

Seven ARCH processes are included in this study. They share a common value of $\mu$, which is 0 . Values of other parameters are detailed in Table 3. Notice that the first four processes do not have linear signals $\left(\phi_{1}=0, \theta_{1}=0\right)$, whereas the fifth and the sixth processes are associated with an $\operatorname{AR}(1)$ linear signal ( $\phi_{1}=0.6$ ), and the last process has a MA(1) linear signal $\left(\theta_{1}=-0.6\right)$.

### 3.4. GARCH Processes

A generalized version of the ARCH process, known as the generalized ARCH (GARCH) process, was introduced by Bollerslev (1986). GARCH generalizes Engle's ARCH process by adding additional conditional autoregressive terms. An $\operatorname{ARMA}(p, q)$ process with a GARCH error term of $\operatorname{order}\left(p^{\prime}, q^{\prime}\right), \operatorname{ARMA}(p, q)$ $\operatorname{GARCH}\left(p^{\prime}, q^{\prime}\right)$, can be written as

$$
\begin{align*}
& r_{t}=\mu+\sum_{i=1}^{p} \phi_{i} r_{t-i}+\sum_{j=1}^{q} \theta_{j} \varepsilon_{t-j}+\varepsilon_{t}  \tag{14}\\
& \varepsilon_{t} \mid \Omega_{t-1} \sim N\left(0, \sigma_{t}^{2}\right)  \tag{15}\\
& \sigma_{t}^{2}=\omega+\sum_{m=1}^{q^{\prime}} \alpha_{m} \varepsilon_{t-m}^{2}+\sum_{n=1}^{p^{\prime}} \beta_{n} \sigma_{t-n}^{2} \tag{16}
\end{align*}
$$

Table 4. Data Generating Processes - GARCH.

| Code | Model |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | $\beta_{1}$ | $\beta_{2}$ | $\alpha_{1}$ | $\alpha_{2}$ | $\phi_{1}$ | $\theta_{1}$ |
| GH-1 | AR(0)-GARCH(1,1) | 0.3 | 0 | 0.5 | 0 | 0 | 0 |
| GH-2 | AR(0)-GARCH(1,1) | 0.5 | 0 | 0.3 | 0 | 0 | 0 |
| GH-3 | AR(0)-GARCH(1,2) | 0.2 | 0 | 0.2 | 0.4 | 0 | 0 |
| GH-4 | AR(0)-GARCH(1,2) | 0.2 | 0 | 0.4 | 0.2 | 0 | 0 |
| GH-5 | AR(0)-GARCH $(2,1)$ | 0.2 | 0.4 | 0.2 | 0 | 0 | 0 |
| GH-6 | AR(0)-GARCH(2,1) | 0.4 | 0.2 | 0.2 | 0 | 0 | 0 |
| GH-7 | AR(1)-GARCH(1,1) | 0.5 | 0 | 0.3 | 0 | 0.6 | 0 |
| GH-8 | AR(1)-GARCH(1,2) | 0.2 | 0 | 0.4 | 0.2 | 0.6 | 0 |
| GH-9 | AR(1)-GARCH(2,1) | 0.4 | 0.2 | 0.2 | 0 | 0.6 | 0 |
| GH-10 | MA(1)-GARCH(1,1) | 0.3 | 0 | 0.5 | 0 | 0 | -0.6 |

with $\omega>0, \alpha_{m}=0$ and $\beta_{n} \geq 0, m=1, \ldots, q^{\prime}, n=1, \ldots, p^{\prime}$. Again, $\Omega_{t}$ denotes the information set available at time $t$.

Nine GARCH processes are attempted. In all cases, $u=0$ and $\omega=0.001$. Specifications of other parameters are given in Table 4. The 7th, 8th and 9th models (GH-7, GH-8, GH-9) are AR(1) processes combined with a GARCH error term, whereas the last model (GH-10) is a MA(1) process plus a GARCH error term. For the remaining six, there are no linear signals but just pure GARCH processes.

### 3.5. Threshold Processes

Tong (1983) proposed a threshold autoregressive (TAR) model which is of the form,

$$
\begin{equation*}
r_{t}=\mu^{(l)}+\sum_{i=1}^{p} \phi_{i}^{(l)} r_{t-i}+\varepsilon_{t} \tag{17}
\end{equation*}
$$

if $r_{t-d} \in \Omega_{1}(l=1,2, \ldots, k)$, where $\Omega_{i} \cap \Omega_{j}=\varnothing(i, j=1, \ldots, k)$ if $i \cdot j$ and $\cup_{l=1}^{k} \Omega_{l}=\Re$. The parameter $k$ represents the number of thresholds and $d$ is called the threshold lag (or delay parameter). Producing various limit cycles is one of the important features of the threshold models, and the TAR process can be applied to the time series which has an asymmetric cyclical form.

The threshold idea can be used as a module to add and to extend other processes. Here, we apply the threshold idea to the bilinear process (10), and extend it to a threshold bilinear (TBL) process. Let us denote a bilinear process $(\mathrm{BL}(p, q, u, v))$

Table 5. Data Generating Processes - Threshold Processes.

| Code | Model | Parameters |  |  |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\phi_{1}^{(1)} \phi_{1}^{(2)}$ | $\phi_{2}^{(1)} \phi_{2}^{(2)}$ | $\theta_{1}^{(1)} \theta_{1}^{(2)}$ | $\psi_{11}^{(1)} \psi_{11}^{(2)}$ | $\psi_{12}^{(1)} \psi_{12}^{(2)}$ | $\psi_{21}^{(1)} \psi_{21}^{(2)}$ | $\psi_{22}^{(1)} \psi_{22}^{(2)}$ |
| TH-1 | TBL $(2 ; 1,0,0,0)$ | 0.3 | 0 | 0 | 0 | 0 | 0 | 0 |
|  |  | 0.6 | 0 | 0 | 0 | 0 | 0 | 0 |
| TH-2 | TBL $(2 ; 1,1,0,0)$ | 0.3 | 0 | 0.6 | 0 | 0 | 0 | 0 |
|  |  | 0.6 | 0 | 0.3 | 0 | 0 | 0 | 0 |
| TH-3 | TBL $(2 ; 0,0,1,1)$ | 0 | 0 | 0 | 0.3 | 0 | 0 | 0 |
|  |  | 0 | 0 | 0 | 0.6 | 0 | 0 | 0 |
| TH-4 | TBL $(2 ; 1,1,2,2)$ | 0.3 | 0 | 0 | 0 | 0 | 0.6 | 0 |
|  |  | 0 | 0 | 0.3 | 0 | 0.6 | 0 | 0 |
| TH-5 | TBL $(2 ; 2,0,2,2)$ | 0 | 0 | 0 | 0.3 | 0 | 0 | -0.6 |
|  |  | 0.3 | -0.6 | 0 | 0 | 0 | 0 | 0 |

Note: The lag period $d$ is set to 1 and $\mu^{(1)}=\mu^{(2)}=0$ in all of the models. In addition, $\Omega_{1} \equiv\left\{r_{t-d} \mid r_{t-d} \geq 0\right\}$ and $\Omega_{2} \equiv\left\{r_{t-d} \mid r_{t-d}<0\right\}$.
with $k$-thresholds by $\operatorname{TBL}(k, p, q, u, v)$, which can be written as

$$
\begin{equation*}
r_{t}=\mu^{(l)}+\sum_{i=1}^{p} \phi_{i}^{(l)} r_{t-i}+\sum_{j=1}^{q} \theta_{j}^{(l)} \varepsilon_{t-j}+\sum_{m=1}^{u} \sum_{n=1}^{v} \psi_{m n}^{(l)} r_{t-m} \varepsilon_{t-n}+\varepsilon_{t} \tag{18}
\end{equation*}
$$

It is trivial to show that TBL can be reduced to a threshold ARMA if $\psi_{m m}^{(l)}=0$ for all $m, n$ and $l$. Table 5 lists the five TBL processes considered in this paper. The motives for choosing these five series will become clear when we come to Section 6.4.

### 3.6. Chaotic Processes

All of the above-mentioned processes are stochastic. However, the time series that appear to be random does not necessary imply that they are generated from a stochastic process. Chaotic time series as an alternative description of this seemingly random phenomenon was a popular econometrics topic in the 1990s. While it is hard to believe that a financial time series is just a deterministic chaotic time series, the chaotic process can still be an important module for the working of a nonlinear time series. Five chaotic processes are employed in this study.

## C-1: Logistic Map

$$
\begin{equation*}
r_{t}=4 r_{t-1}\left(1-r_{t-1}\right), \quad r_{t} \in[0,1] \quad \forall t \tag{19}
\end{equation*}
$$

C-2: Henon Map

$$
\begin{equation*}
r_{t}=1+0.3 r_{t-2}-1.4 r_{t-1}^{2}, \quad r_{-1}, r_{0} \in[-1,1] \tag{20}
\end{equation*}
$$

C-3: Tent Map

$$
\begin{cases}r_{t}=2 r_{t-1}, & \text { if } 0 \leq r_{t-1}<0.5  \tag{21}\\ r_{t}=2\left(1-r_{t-1}\right), & \text { if } 0.5 \leq r_{t-1} \leq 1\end{cases}
$$

C-4: Poly. 3

$$
\begin{equation*}
r_{t}=4 r_{t-1}^{3}-3 r_{t-1}, \quad r_{t} \in[-1,1] \quad \forall t \tag{22}
\end{equation*}
$$

C-5: Poly. 4

$$
\begin{equation*}
r_{t}=8 r_{t-1}^{4}-8 r_{t-1}^{2}+1, \quad r_{t} \in[-1,1] \quad \forall t \tag{23}
\end{equation*}
$$

The series generated by all these stochastic processes (from Sections 3.1 to 3.6) may have a range which does not fit the range of the normal return series. For example, the process (19) is always positive. As a result, a contracting or a dilating map is needed. We, therefore, contract or dilate all series linearly and monotonically into an acceptable range, which is $(-0.3,0.3)$ in this paper.

## 4. PERFORMANCE CRITERIA AND STATISTICAL TESTS

Basic performance metrics to evaluate the performance of trading strategies have long existed in the literature. Following Refenes (1995), we consider the following four main criteria: returns, the winning probability, the Sharpe ratio and the luck coefficient. In this paper, the performance of the trading strategies generated by the ordinal genetic algorithm (OGA) is compared with that using a benchmark based on these four criteria. To make the evaluation process rigorous, performance differences between the OGA-based trading strategies and the benchmark are tested statistically. Tests for returns and winning probability are straightforward. Tests for the Sharpe ratio are available in the literature (see, for example, Jobson and Korkie (1981) and Arnold (1990)). However, tests for the luck coefficient are more demanding, and it has not been derived in the literature. In this paper, we develop asymptotic tests for the luck coefficient.

### 4.1. Returns

Let $X$ and $Y$ be the accumulated returns of an one-dollar investment by applying OGA-based trading strategies and the benchmark strategy, say, the buy-and-hold
$(\mathrm{B} \& \mathrm{H})$ strategy, respectively. Assume that $E(X)=\mu$ and $E(Y)=\nu$. Let us estimate the $\mu$ and $\nu$ by the respective sample average $\bar{\pi}^{2}$ and $\bar{\pi}^{1}$ via the Monte Carlo simulation. Then one can test the null

$$
\begin{equation*}
H_{0}: \mu-n \leq 0, \tag{24}
\end{equation*}
$$

with the following test statistic

$$
\begin{equation*}
Z_{\pi}=\frac{\sqrt{n}\left(\bar{\pi}^{2}-\bar{\pi}^{1}\right)}{\left(\hat{\sigma}^{2}+\hat{\tau}^{2}-2 \hat{\rho} \hat{\sigma} \hat{\tau}\right)^{1 / 2}} \tag{25}
\end{equation*}
$$

where $\hat{\sigma}^{2}$ and $\hat{\tau}^{2}$ are the sample variances of $X$ and $Y, \hat{\rho}$ is the sample correlation coefficient of $X$ and $Y$, and $n$ is the sample size (the number of ensembles generated during the Monte Carlo simulation). By using the central limit theorem, it is straightforward to show that $Z_{\pi}$ is an asymptotically standard normal test.

While testing the difference between $\bar{\pi}^{2}$ and $\bar{\pi}^{1}$ can tell us the performance of the GA as opposed to a benchmark, it provides us with nothing more than a point evaluation. In some cases, we may also wish to know whether the superiority, if shown, can extend to a large class of trading strategies. A common way to address this question is to introduce an omniscient trader. Let us denote the respective accumulated returns earned by this omniscient trader as $\bar{\pi}^{*} .4$ Now, subtracting $\bar{\pi}^{1}$ from $\bar{\pi}^{*}$ gives us the total unrealized gain, if we only know the benchmark. Then, the ratio, also called the exploitation ratio,

$$
\begin{equation*}
\tilde{\pi} \equiv \frac{\bar{\pi}^{2}-\bar{\pi}^{1}}{\bar{\pi}^{*}-\bar{\pi}^{1}} \tag{26}
\end{equation*}
$$

is a measure of the size of those unrealized gains which can be exploited by using a GA. Based on its formulation, $\tilde{\pi}$ may be positive, negative or zero, but has one as its maximum. If $\tilde{\pi}$ is not only positive, but is also close to one, then its superiority is not just restricted to the benchmark, but may also have global significance.

In addition to the accumulated gross returns, one can also base the comparison on the excess return by simply subtracting one from the accumulated gross returns. A relative superiority measure of the GA as opposed to the benchmark can be defined accordingly as

$$
\begin{equation*}
\dot{\pi} \equiv \frac{\left(\bar{\pi}^{2}-1\right)-\left(\bar{\pi}^{1}-1\right)}{\left|\bar{\pi}^{1}-1\right|}=\frac{\bar{\pi}^{2}-\bar{\pi}^{1}}{\left|\bar{\pi}^{1}-1\right|} \tag{27}
\end{equation*}
$$

### 4.2. Winning Probability

The mean return can sometimes be sensitive to outliers. Therefore, it is also desirable to base our performance criterion on some robust statistics, and the
winning probability is one of this kind. The winning probability basically tells us, by randomly picking up an ensemble from one stochastic process, the probability that the GA will win. Formally, let $(X, Y)$ be a random vector with the joint density function $h(x, y)$. Then $p_{w}$, defined as follows, is called the winning probability.

$$
\begin{equation*}
p_{w}=\operatorname{Pr}(X>Y)=\iint_{x>y} h(x, y) \mathrm{d} x \mathrm{~d} y \tag{28}
\end{equation*}
$$

Based on the winning probability, we can say that $X$ is superior to $Y$ if $p_{w}>0.5$, and inferior to $Y$ if $p_{w}<0.5$, and equivalent to $Y$ if $p_{w}=0.5$. The null hypothesis to test is

$$
\begin{equation*}
H_{0}: p_{w} \leq 0.5 \tag{29}
\end{equation*}
$$

The rejection of (29) shows the superiority of the GA over the benchmark. An asymptotic standard normal test of (29) can be derived as

$$
\begin{equation*}
Z_{w}=\frac{\sqrt{n}\left(\hat{p}_{w}-0.5\right)}{\sqrt{\hat{p}_{w}\left(1-\hat{p}_{w}\right)}} \tag{30}
\end{equation*}
$$

where $\hat{p}_{w}$ is the sample counterpart of $p_{w}$.

### 4.3. Sharpe Ratio

One criterion which has been frequently ignored by machine learning people in finance is the risk associated with a trading rule. Normally, a higher profit known as the risk premium is expected when the associated risk is higher. Without taking the risk into account, we might exaggerate the profit performance of a highly risky trading rule. Therefore, to evaluate the performance of our GA-based trading rule on a risk-adjusted basis, we have employed the well-known Sharpe ratio as the third performance criterion (Sharpe, 1966). The Sharpe ratio $s$ is defined as the excess return divided by a risk measure. The higher the Sharpe ratio, the higher the risk-adjusted return.

Formally, let $X \sim f(x)$ with $E(X)=\mu$ and $\operatorname{Var}(X)=\sigma^{2}$. Then the value

$$
\begin{equation*}
s=\frac{\mu-c}{\sigma} \tag{31}
\end{equation*}
$$

is called the Sharpe ratio of $X$ where $c$ is one plus a risk-free rate. Furthermore, to compare the performance of two trading strategies in the Sharpe ratio, let $X \sim f(x)$ and $Y \sim g(y)$ with $E(X)=\mu, E(Y)=\nu, \operatorname{Var}(X)=\sigma^{2}$ and $\operatorname{Var}(Y)=\tau^{2}$. Then the difference

$$
\begin{equation*}
d=\frac{\mu-c}{\sigma}-\frac{v-c}{\tau} \tag{32}
\end{equation*}
$$

is called the Sharpe-ratio differential between $X$ and $Y$. Accordingly, $X$ is said to have a higher (lower) Sharpe ratio relative to $Y$ if $d>0(d<0)$. Otherwise, $X$ and $Y$ are said to be identical in terms of the Sharpe ratio.

Jobson and Korkie (1981) derive an asymptotic standard normal test for the Sharpe-ratio differential. However, we do not follow their Taylor expansion formulation. Instead, by applying Slutzky's theorem, the Cramer $\delta$ theorem, and the multivariate central limit theorem, a standard normal test for the null

$$
\begin{equation*}
H_{0}: d \leq 0 \tag{33}
\end{equation*}
$$

can be derived as follows:

$$
\begin{equation*}
Z_{d}=\frac{\sqrt{n}(\hat{d}-d)}{\hat{\omega}_{1}} \tag{34}
\end{equation*}
$$

where

$$
\begin{equation*}
\hat{d}=\frac{\bar{\pi}^{2}-c}{\hat{\sigma}}-\frac{\bar{\pi}^{1}-c}{\hat{\tau}} \tag{35}
\end{equation*}
$$

and

$$
\begin{aligned}
\hat{\omega}_{1}^{2}= & 2(1-\hat{\rho})+\frac{\left(\bar{\pi}^{2}-c\right)}{\hat{\sigma}}(\bar{\theta}-\hat{\delta})+\frac{\left(\bar{\pi}^{1}-c\right)}{\hat{\tau}}(\hat{\psi}-\hat{\xi}) \\
& -\frac{\left(\bar{\pi}^{2}-c\right)\left(\bar{\pi}^{1}-c\right)}{\hat{\sigma} \hat{\tau}} \frac{(\hat{\phi}-1)}{2}+\frac{\left(\bar{\pi}^{2}-c\right)^{2}}{\hat{\sigma}^{2}} \frac{(\hat{\gamma}-1)}{4}+\frac{\left(\bar{\pi}^{1}-c\right)^{2}}{\hat{\tau}} \frac{(\hat{\eta}-1)}{4}
\end{aligned}
$$

$\hat{\delta}, \hat{\gamma}, \hat{\xi}$ and $\hat{\eta}$ are the corresponding sample third and fourth moments of $X$ and $Y$, whereas $\hat{\rho}, \hat{\theta}, \hat{\psi}, \hat{\phi}$ are the corresponding sample mixed moments between $X$ and $Y$ (also expressed as Eq. (37)).

$$
\left[\begin{array}{c}
\frac{E(X-u)^{3}}{\sigma^{3}}  \tag{37}\\
\frac{E(X-u)^{4}}{\sigma^{4}} \\
\frac{E(Y-v)^{3}}{\tau^{3}} \\
\frac{E(Y-v)^{4}}{\tau^{4}}
\end{array}\right]=\left[\begin{array}{c}
\delta \\
\gamma \\
\xi \\
\eta
\end{array}\right],\left[\begin{array}{l}
\frac{E(X-u) E(X-v)}{\sigma \tau} \\
\frac{E(X-u)^{2}(Y-v)}{\sigma^{2} \tau} \\
\frac{E(X-u)(Y-v)^{2}}{\sigma \tau^{2}} \\
\frac{E(x-u)^{2}(Y-v)^{2}}{\sigma^{2} \tau^{2}}
\end{array}\right]=\left[\begin{array}{c}
\rho \\
\theta \\
\psi \\
\phi
\end{array}\right]
$$

### 4.4. Luck Coefficient

The largest positive trade can be very important if it makes a significant contribution towards skewing the average profit dramatically. When this happens, people can be severely misled by the sample mean. As a solution to this problem, the trimmed mean is often used in statistics. A similar idea in finance is known as the luck coefficient. The luck coefficient $l_{\varepsilon}$ is defined as the sum of the largest $100 \%$ returns, $\varepsilon \in(0,1)$, divided by the sum of total returns. In a sense, the larger the luck coefficient, the weaker the reliability of the performance. The luck coefficient, as a performance statistic, is formally described below.

Let $\left\{X_{1}, X_{2}, \ldots, X_{m}\right\}$ be a random sample from $f(x)$ with $E(X)=\mu$. The order statistic of this random sample can be enumerated as $X_{(1)}, X_{(2)}, \ldots, X_{(m)}$, where $X_{(1)} \leq X_{(2)} \leq \ldots \leq X_{(m)}$. Then, from the order statistics, it is well known that

$$
\begin{equation*}
X_{(m)} \sim g\left(x_{(m)}\right)=m\left[F\left(x_{(m)}\right)\right]^{m-1} f\left(x_{(m)}\right) \tag{38}
\end{equation*}
$$

where $F$ is the distribution function of $X$. Furthermore, let $X_{i} \stackrel{i i d}{\sim} f(x), i=1,2, \ldots$, $m$ and $X_{(m)} \sim g\left(x_{(m)}\right)$ as described above with $E\left(X_{(m)}\right)=\mu$. Then the ratio

$$
\begin{equation*}
l_{\varepsilon}=\frac{\varepsilon \mu_{\varepsilon}}{\mu} \tag{39}
\end{equation*}
$$

is called the luck coefficient of $X$ where $\varepsilon=\frac{1}{m}$. In this study, is set to 0.05 . Here we want to see how much of the contribution to mean returns comes from the largest 5\% of trades.

For making a comparison between strategies, the luck-coefficient ratio is defined as follows. Let $X_{i} \stackrel{i i d}{\sim} f_{x}(x)$ with $E(X)=\mu, Y_{i} \stackrel{i d}{\sim} f_{y}(y)$ with $E(Y)=v, i=1,2, \ldots$, $m$ and $X_{(m)} \sim g_{x}\left(x_{(m)}\right)$ with $E\left(X_{(m)}\right)=\mu, Y_{(m)} \sim g_{y}\left(y_{(m)}\right)$ with $E\left(Y_{(m)}\right)=\nu$. Then the ratio

$$
\begin{equation*}
r_{\varepsilon}=\frac{\varepsilon v_{\varepsilon} / v}{\varepsilon \mu_{\varepsilon} / \mu}=\frac{\mu v_{\varepsilon}}{\nu \mu_{\varepsilon}} \tag{40}
\end{equation*}
$$

is called the luck-coefficient ratio of $X$ relative to $Y$ where $\varepsilon=\frac{1}{m}$. Based on this definition, $X$ is said to have a lower (higher) luck coefficient relative to $Y$ if $r>1$ $(r<1)$. Otherwise, $X$ and $Y$ are said to be identical in terms of the luck coefficient. However, to the best of our knowledge, the respective asymptotic standard normal test for the null

$$
\begin{equation*}
H_{0}: r \leq 1 \tag{41}
\end{equation*}
$$

is not available in the literature. Nevertheless, similar to the derivation of the test of the Sharpe ratio (34), it is not hard to cook up such a test by using Slutzky's theorem, the Cramer $\delta$ theorem, and the multivariate central limit theorem, which
is given in Eq. (42)

$$
\begin{equation*}
Z_{r}=\frac{\sqrt{n}\left(\hat{r}_{\varepsilon}-r_{\varepsilon}\right)}{\hat{\omega}_{2}} \tag{42}
\end{equation*}
$$

where

$$
\begin{equation*}
\hat{r}_{\varepsilon}=\frac{\bar{\pi}^{2} \bar{\pi}_{m}^{1}}{\bar{\pi}^{1} \bar{\pi}_{m}^{2}} \tag{43}
\end{equation*}
$$

and

$$
\begin{align*}
\hat{\omega}_{2}^{2}= & \frac{\varepsilon\left(\bar{\pi}_{m}^{1}\right)^{2}}{\left(\bar{\pi}^{1}\right)^{2}\left(\bar{\pi}_{m}^{2}\right)^{2}}\left(\hat{\sigma}^{2}+\frac{\left(\bar{\pi}^{2}\right)^{2} \hat{\tau}^{2}}{\left(\bar{\pi}^{2}\right)^{2}}\right)+\frac{\left(\bar{\pi}^{2}\right)^{2}}{\left(\bar{\pi}^{1}\right)^{2}\left(\bar{\pi}_{m}^{2}\right)^{2}}\left(\hat{\tau}_{\varepsilon}^{2}+\frac{\left(\bar{\pi}_{m}^{1}\right)^{2} \hat{\sigma}_{\varepsilon}^{2}}{\left(\bar{\pi}_{m}^{2}\right)^{2}}\right) \\
& -\frac{2 \bar{\pi}^{2} \bar{\pi}_{m}^{1} \hat{\tau}}{\left(\bar{\pi}^{1}\right)^{3}\left(\bar{\pi}_{m}^{2}\right)^{2}}\left(\varepsilon \bar{\pi}_{m}^{1} \hat{\rho} \hat{\sigma}+\bar{\pi}^{2} \hat{\lambda} \hat{\tau}_{\varepsilon}\right)-\frac{2 \bar{\pi}^{2} \bar{\pi}_{m}^{1} \hat{\sigma}_{\varepsilon}}{\left(\bar{\pi}^{1}\right)^{2}\left(\bar{\pi}_{m}^{2}\right)^{3}}\left(\bar{\pi}_{m}^{1} \hat{\sigma} \hat{\imath}+\bar{\pi}^{2} \hat{\tau}_{\varepsilon} \hat{\zeta}\right) \\
& +\frac{2 \bar{\pi}^{2} \bar{\pi}_{m}^{1}}{\left(\bar{\pi}^{1}\right)^{2}\left(\bar{\pi}_{m}^{2}\right)^{2}}\left(\hat{\sigma} \hat{\kappa} \hat{\tau}_{\varepsilon}+\frac{\bar{\pi}^{2} \bar{\pi}_{m}^{1} \hat{\sigma}_{\varepsilon} \hat{\sigma} \hat{\tau}}{\bar{\pi}^{1} \bar{\pi}_{m}^{2}}\right) \tag{44}
\end{align*}
$$

$\bar{\pi}_{m}^{1}$ and $\bar{\pi}_{m}^{2}$ are the corresponding sample means of $Y_{(m)}$ and $X_{(m)} . \hat{\tau}_{\varepsilon}^{2}$ and $\hat{\sigma}_{\varepsilon}^{2}$ are the corresponding sample variances of $Y_{(m)}$ and $X_{(m)}$, and $\hat{\rho}, \hat{\zeta}, \hat{\kappa}, \hat{\imath}, \hat{\lambda}$, and $\hat{o}$ are the corresponding sample correlation coefficients as indicated in Eq. (45).

$$
\left[\begin{array}{l}
\operatorname{corr}\left(X_{i}, Y_{i}\right)  \tag{45}\\
\operatorname{corr}\left(X_{(m)}, Y_{(m)}\right) \\
\operatorname{corr}\left(X_{i}, Y_{(m)}\right)
\end{array}\right]=\left[\begin{array}{l}
\rho \\
\zeta \\
\kappa
\end{array}\right],\left[\begin{array}{l}
\operatorname{corr}\left(X_{i}, X_{(m)}\right) \\
\operatorname{corr}\left(Y_{i}, Y_{(m)}\right) \\
\operatorname{corr}\left(Y_{i}, X_{(m)}\right)
\end{array}\right]=\left[\begin{array}{c}
\iota \\
\lambda \\
o
\end{array}\right]
$$

## 5. MONTE CARLO SIMULATION

Since it is hard to obtain analytical results of the performance of the GA in relation to various stochastic processes, Monte Carlo simulation methodology is used in this study. Each stochastic process listed in Tables 1-5 and Eqs (19) to (23) is used to generate 1000 independent time series, each with 105 observations $\left(\left\{r_{t}\right\}_{t=1}^{105}\right) .{ }^{5}$ For each series, the first 70 observations $\left(\left\{r_{t}\right\}_{t=1}^{70}\right)$ are taken as the training sample, and the last 35 observations $\left(\left\{r_{t}\right\}_{t=76}^{105}\right)$ are used as the testing sample. The OGA are then employed to extract trading strategies from these training samples. These strategies are further tested by the testing samples, and the resulting accumulated returns ( $p$ ) are calculated, i.e.

$$
\begin{equation*}
\pi=\prod_{t=76}^{105}\left(1+r_{t}\right) \tag{46}
\end{equation*}
$$

In the meantime, the accumulated returns of the benchmark are also calculated. In following convention, our choice of the benchmark is simply the buy-and-hold ( $\mathrm{B} \& \mathrm{H}$ ) strategy.

Let $\pi_{i}^{1}(i=1,2, \ldots, 1000)$ be the accumulated returns of the B\&H strategy when tested on the $i$ th ensemble of a stochastic process, and $\pi_{i}^{2}$ be the accumulated returns of the OGA when tested on the same ensemble. The issue which we shall address, given the set of observations $S\left(\equiv\left\{\pi_{i}^{1}, \pi_{i}^{2}\right\}_{i=1}^{1000}\right)$, is to decide whether the OGA-based trading strategies can statistically significantly outperform the $B \& H$ strategy under the stochastic process in question. The answers are given in the next section.

## 6. TEST RESULTS

### 6.1. ARMA Processes

We start our analysis from the linear stochastic processes. Table 6 summarizes the statistics defined in Section 4. Several interesting features stand out. First, from the statistics $\hat{p}_{w}$ and $z_{w}$, it can be inferred that, in accumulated returns, the probability that the OGA-based trading strategies can beat the $\mathrm{B} \& \mathrm{H}$ strategy is significantly greater than 0.5 . For the stochastic processes with linear signals (L-1-L-12), the winning probability $\hat{p}_{w}$ ranges from 0.713 (L-5) to 0.991 (L-12). What, however, seems a little puzzling is that, even in the case of white noise (L-13), the GA can also beat $\mathrm{B} \& \mathrm{H}$ statistically significantly, while with much lower winning probabilities $p_{w}$ (0.606). This seemingly puzzling finding may be due to the fact that a pseudorandom generator can actually generate a series with signals when the sample size is small. For example, Chen and Tan (1999) show that, when the sample size is 50 , the probability of having signals in a series generated from a pseudo-random generator is about $5 \%$, while that probability can go to zero when the sample size is 1000 . Therefore, by supposing that the OGA-based trading strategies can win in all these atypical ensembles and get even with the B\&H strategy in other normal ensembles, then $\hat{p}_{w}$ can still be significantly greater than 0.5 .

Second, by directly comparing $\bar{\pi}^{1}$ with $\bar{\pi}^{2}$, we can see that, except for the case of white noise, the OGA-based trading strategies unanimously outperform the $\mathrm{B} \& \mathrm{H}$ strategy numerically in all linear $\operatorname{ARMA}(p, q)$ processes. From the $\dot{\pi}$ statistic (27), we see that the triumph of GA over B\&H extends from a low of $19 \%$ (L-10) to a high of $916 \%$ (L-3). The $z_{p}$ statistic, ranging from 2.12 to 47.39, signifies the statistical significance of these differences. Third, to see how the GA effectively exploited the excess potential returns earned by the omniscient trader, $\tilde{\pi}$ is also included in Table 6. There it is observed that the GA exploited $2-31 \%$


Table 6. Performance Statistics of the OGA and B\&H - ARMA.

Note: $\bar{\pi}^{1}, \bar{\pi}^{2}$ and $\bar{\pi}^{*}$ are the respective sample mean return of OGA, B\&H and the omniscient trader. $\tilde{\pi}$ is the exploitation ratio (Eq. 26), and $\dot{\pi}$ is the relative superiority index (Eq. 27). $\hat{p}_{w}$ is the sample winning probability of OGA over B\&H (Eq. 28). $\hat{s}_{1}$ and $\hat{s}_{2}$ are the corresponding sample Sharpe ratio of OGA and B\&H (Eq. (31)). Their sample difference is $\hat{d}$ (Eq. (32)). $\hat{l}_{0.05}^{1}$ and $\hat{l}_{0.05}^{2}$ are the sample luck coefficient of OGA and B\&H (Eq. (39)), and $\hat{r}_{0.05}$ is the sample luck coefficient ratio between the two (Eq. (40)). The $z_{\pi}, z_{w}, z_{d}$ and $z_{r}$ are the test statistics of the mean return difference, winning probability, Sharpe ratio differential, and luck coefficient ratio, respectively. The critical value of them is 1.28 at the $10 \%$ significance level, and is 1.64 at the 5\% significance level.
of the potential excess returns. However, as we expect, it was to no avail when the scenario changed to white noise.

As mentioned earlier, we should not judge the performance of the GA solely by the profitability criterion. The risk is a major concern in business practice.

We, therefore, have also calculated the Sharpe ratio, a risk-adjusted profitability criterion. It is interesting to notice that in all cases the Sharpe-ratio differential $(\hat{d})$ is positive. In other words, the GA still outperforms $\mathrm{B} \& \mathrm{H}$ even after taking into account the risk. The test of this differential also lends support to its statistical significance.

Finally, we examine whether the GA wins just by luck in the sense that its return performance depends heavily on its best 5\% trades. Based on the statistic of luck coefficient $\hat{r}_{0.05}$, it is found that in only one of the 13 cases, i.e. the case L-12, dose the GA have a higher luck coefficient; in the other 12 cases, the luck-coefficient ratios are larger than 1 , meaning that the dominance of the GA over $\mathrm{B} \& \mathrm{H}$ cannot be attributed to the presence of a few abnormally large returns. From the test $z_{r}$, this result is again significant except for the case L-9. All in all, we can conclude that if the return follows a simple linear ARMA process, then the superior performance of the GA compared to $\mathrm{B} \& \mathrm{H}$ is expected.

### 6.2. Bilinear Processes

By moving into the bilinear processes, we are testing the effectiveness of the GA when the return series is nonlinear. Table 7 summarizes all the key statistics. Obviously, the performance of the GA is not as glamorous as before. Out of the eight battles, it loses twice (cases BL-1 and BL-2) to B\&H (see $z_{p}$ and $z_{w}$ ). Taking the risk into account would not help reverse the situation (see $z_{d}$ ). It is, however, interesting to notice a unique feature shared by BL-1 and BL-2. As mentioned in Section 3.2, the two stochastic processes do not have any linear component (all $\phi_{i}$ and $\theta_{j}$ in Eq. (10) or Table 2 are zero). In other words, these two cases are pure nonlinear (pure bilinear). If some linear components are added back to the series, then the significant dominance of the GA does come back. This is exactly what happens in the other six cases (BL-3 to BL-8), which all have the ARMA component as a part (Table 2).

Even for the six cases where the GA wins, we can still observe some adverse impacts of nonlinearity on the GA. Roughly speaking, Table 7 shows that the distribution of both $\dot{\pi}$ and $\tilde{\pi}$ becomes lower as opposed to those items observed in the linear stochastic processes. So, not only does the advantage of the GA relative to $\mathrm{B} \& \mathrm{H}$ shrink, but its disadvantage relative to the omniscient also becomes larger.

However, nonlinearity does not change many of the results in relation to the luck coefficients. The luck-coefficient ratios are all higher than 1 , and most of the results are statistically significant, indicating the relative stability of the GA.

Table 7. Performance Statistics of the OGA and B\&H - Bilinear.

| Code | Model | $\bar{\pi}^{1}$ | $\bar{\pi}^{2}$ | $\bar{\pi}^{*}$ | $z_{\pi}$ | $\tilde{\pi}(\%)$ | $\dot{\pi}(\%)$ | $\hat{p}_{w}$ | $z_{w}$ |
| :--- | :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | ---: |
| BL-1 | BL(0,0,1,1) | 1.253 | 1.126 | 4.398 | -6.78 | -4 | -50 | 0.491 | -0.57 |
| BL-2 | BL(0,0,1,1) | 1.151 | 1.064 | 4.228 | -4.66 | -3 | -58 | 0.517 | 1.08 |
| BL-3 | BL(0,1,1,2) | 1.302 | 1.830 | 5.341 | 11.50 | 13 | 175 | 0.861 | 17.78 |
| BL-4 | BL(0,1,1,2) | 1.186 | 1.356 | 4.449 | 6.95 | 5 | 91 | 0.745 | 17.78 |
| BL-5 | BL(1,0,2,1) | 1.260 | 1.419 | 4.539 | 5.07 | 5 | 61 | 0.747 | 17.97 |
| BL-6 | BL(1,0,2,1) | 2.292 | 3.143 | 7.226 | 9.89 | 17 | 66 | 0.877 | 36.30 |
| BL-7 | BL(1,1,2,2) | 1.841 | 2.471 | 6.448 | 8.83 | 14 | 75 | 0.848 | 30.65 |
| BL-8 | BL(1,1,2,2) | 1.602 | 2.287 | 5.894 | 19.57 | 16 | 114 | 0.870 | 34.79 |
| Code | Model | $\hat{s}_{1}$ | $\hat{s}_{2}$ | $\hat{d}$ | $z_{d}$ | $\hat{l}_{0.05}^{1}$ | $\hat{l}_{0.05}^{2}$ | $\hat{r}_{0.05}$ | $z_{r}$ |
| BL-1 | BL(0,0,1,1) | 0.316 | 0.251 | -0.065 | -3.29 | 0.132 | 0.105 | 1.256 | 3.30 |
| BL-2 | BL(0,0,1,1) | 0.190 | 0.144 | -0.046 | -2.21 | 0.144 | 0.101 | 1.427 | 4.14 |
| BL-3 | BL(0,1,1,2) | 0.167 | 0.425 | 0.259 | 7.31 | 0.182 | 0.124 | 1.793 | 3.08 |
| BL-4 | BL(0,1,1,2) | 0.162 | 0.724 | 0.562 | 16.32 | 0.232 | 0.129 | 1.465 | 3.22 |
| BL-5 | BL(1,0,2,1) | 0.178 | 0.465 | 0.287 | 13.53 | 0.211 | 0.138 | 1.531 | 3.54 |
| BL-6 | BL(1,0,2,1) | 0.251 | 0.539 | 0.289 | 10.38 | 0.346 | 0.226 | 1.534 | 2.05 |
| BL-7 | BL(1,1,2,2) | 0.285 | 0.711 | 0.426 | 9.29 | 0.270 | 0.168 | 1.603 | 2.67 |
| BL-8 | BL(1,1,2,2) | 0.179 | 0.386 | 0.207 | 2.52 | 0.272 | 0.182 | 1.494 | 1.14 |

Note: $\bar{\pi}^{1}, \bar{\pi}^{2}$ and $\bar{\pi}^{*}$ are the respective sample mean return of OGA, B\&H and the omniscient trader. $\tilde{\pi}$ is the exploitation ratio (Eq. (26)), and $\dot{\pi}$ is the relative superiority index (Eq. (27)). $\hat{p}_{w}$ is the sample winning probability of OGA over B\&H (Eq. (28)). $\hat{s}_{1}$ and $\hat{s}_{2}$ are the corresponding sample Sharpe ratio of OGA and B\&H (Eq. (31)). Their sample difference is $\hat{d}$ (Eq. (32)). $\hat{l}_{0.05}^{1}$ and $\hat{l}_{0.05}^{2}$ are the sample luck coefficient of OGA and B\&H (Eq. (39)), and $\hat{r}_{0.05}$ is the sample luck coefficient ratio between the two (Eq. (40)). The $z_{\pi}, z_{w}, z_{d}$ and $z_{r}$ are the test statistics of the mean return difference, winning probability, Sharpe ratio differential, and luck coefficient ratio, respectively. The critical value of them is 1.28 at the $10 \%$ significance level, and is 1.64 at the $5 \%$ significance level.

### 6.3. ARCH and GARCH Processes

As we have already seen from the bilinear processes, nonlinearity can have some adverse effects on the performance of the GA. It would be imperative to know whether this finding is just restricted to a specific class of nonlinear processes or can be generalized to other nonlinear processes. In this and the next two sections, we shall focus on this question, and briefly mention other details when we see the necessity.

Let us first take a look at the results of the other two nonlinear stochastic processes, namely, ARCH and GARCH. Just like what we saw in the bilinear processes, these two classes of processes can become pure nonlinear stochastic if some specific coefficient values are set to zero. This is basically what we do

Table 8. Performance Statistics of the OGA and B\&H - ARCH.

| Code | Model | $\bar{\pi}^{1}$ | $\bar{\pi}^{2}$ | $\bar{\pi}^{*}$ | $z_{\pi}$ | $\tilde{\pi}(\%)$ | $\dot{\pi}(\%)$ | $\hat{p}_{w}$ |
| :--- | :---: | ---: | :---: | :---: | :---: | :---: | :---: | :---: |
| AH-1 AR(0)-ARCH(1) | 1.038 | 1.013 | 3.195 | -1.99 | -1 | -66 | 0.546 | 2.92 |
| AH-2 | AR(0)-ARCH(1) | 1.001 | 1.005 | 4.251 | 0.19 | 0 | 400 | 0.592 |
| AH-3 AR(0)-ARCH(2) | 0.985 | 0.991 | 2.307 | 0.67 | 0 | 40 | 0.562 | 3.92 |
| AH-4 AR(0)-ARCH(2) | 1.007 | 0.997 | 2.268 | -1.09 | -1 | -143 | 0.529 | 1.84 |
| AH-5 AR(1)-ARCH(1) | 1.175 | 1.509 | 2.187 | 22.88 | 33 | 191 | 0.862 | 33.19 |
| AH-6 AR(1)-ARCH(2) | 1.300 | 1.705 | 3.061 | 17.64 | 23 | 135 | 0.838 | 29.01 |
| AH-7 | MA(1)-ARCH(1) | 0.869 | 1.551 | 3.602 | 44.12 | 25 | 521 | 0.959 |
| Code | Model | $\hat{s}_{1}$ | $\hat{s}_{2}$ | $\hat{d}$ | $z_{d}$ | $\hat{l}_{0.05}^{1}$ | $\hat{l}_{0.05}^{2}$ | $\hat{r}_{0.05}$ |
| AH-1 AR(0)-ARCH(1) | 0.170 | 0.038 | -0.032 | -1.33 | 0.117 | 0.091 | 1.285 | 4.53 |
| AH-2 | AR(0)-ARCH(1) | 0.001 | 0.010 | 0.009 | 0.34 | 0.149 | 0.105 | 1.411 |
| AH-3 AR(0)-ARCH(2) | -0.038 | -0.035 | 0.002 | 0.09 | 0.100 | 0.079 | 1.269 | 4.03 |
| AH-4 AR(0)-ARCH(2) | 0.017 | -0.012 | -0.030 | -1.22 | 0.099 | 0.080 | 1.246 | 3.24 |
| AH-5 AR(1)-ARCH(1) | 0.211 | 0.774 | 0.563 | 15.42 | 0.145 | 0.109 | 1.331 | 3.43 |
| AH-6 AR(1)-ARCH(2) | 0.221 | 0.605 | 0.384 | 10.79 | 0.187 | 0.140 | 1.332 | 2.15 |
| AH-7 | MA(1)-ARCH(1) | -0.641 | 1.126 | 1.766 | 35.75 | 0.076 | 0.086 | 0.889 |

Note: $\bar{\pi}^{1}, \bar{\pi}^{2}$ and $\bar{\pi}^{*}$ are the respective sample mean return of OGA, B\&H and the omniscient trader. $\tilde{\pi}$ is the exploitation ratio (Eq. (26)), and $\dot{\pi}$ is the relative superiority index (Eq. 27). $\hat{p}_{w}$ is the sample winning probability of OGA over B\&H (Eq. (28)). $\hat{s}_{1}$ and $\hat{s}_{2}$ are the corresponding sample Sharpe ratio of OGA and B\&H (Eq. (31)). Their sample difference is $\hat{d}$ (Eq. (32)). $\hat{l}_{0.05}^{1}$ and $\hat{l}_{0.05}^{2}$ are the sample luck coefficient of OGA and B\&H (Eq. (39)), and $\hat{r}_{0.05}$ is the sample luck coefficient ratio between the two (Eq. (40)). The $z_{\pi}, z_{w}, z_{d}$ and $z_{r}$ are the test statistics of the mean return difference, winning probability, Sharpe ratio differential, and luck coefficient ratio, respectively. The critical value of them is 1.28 at the $10 \%$ significance level, and is 1.64 at the 5\% significance level.
in Tables 3 and 4. Notice that, based on these settings, AH-1 to AH-4 (ARCH) and GH-1 to GH-6 (GARCH) are all pure nonlinear stochastic processes, i.e. pure ARCH or pure GARCH without linear ARMA components. For the rest, they are a mixture of pure ARCH (GARCH) and linear ARMA processes. Tables 8 and 9 summarize the results of the two stochastic processes. A striking feature is that, in contrast to its performance in mixed processes, the GA performed dramatically worse in pure nonlinear ARCH and GARCH scenarios.

Let us take the ARCH processes as an illustration. In the mixed processes AH-5, AH-6 and AH-7, the GA has a probability of up to $80 \%$ or higher of beating B\&H, and earned $135-521 \%$ more than $\mathrm{B} \& \mathrm{H}$. The fact that these excess returns are not compensation for risk is further confirmed by the Sharpe-ratio differentials which are significantly positive. In addition, the GA exploited $23 \%$ to $33 \%$ of the potential returns earned by the omniscient trader. However, when coming to the pure

Table 9. Performance Statistics of the OGA and B\&H - GARCH.

| Code | Model | $\bar{\pi}^{1}$ | $\bar{\pi}^{2}$ | $\bar{\pi}^{*}$ | $z_{\pi}$ | $\tilde{\pi}(\%)$ | $\pi(\%)$ | $\hat{p}_{w}$ | $z_{w}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| GH-1 | AR(0)-GARCH $(1,1)$ | 0.987 | 0.983 | 2.457 | -0.42 | 0 | -31 | 0.539 | 2.47 |
| GH-2 | $\operatorname{AR}(0)-\operatorname{GARCH}(1,1)$ | 0.968 | 0.979 | 2.580 | 1.19 | 1 | 34 | 0.554 | 3.44 |
| GH-3 | $\operatorname{AR}(0)-\operatorname{GARCH}(1,2)$ | 1.008 | 1.007 | 2.474 | -0.04 | 0 | -13 | 0.544 | 2.79 |
| GH-4 | $\operatorname{AR}(0)-\operatorname{GARCH}(1,2)$ | 0.998 | 1.007 | 2.434 | 0.90 | 1 | 450 | 0.572 | 4.60 |
| GH-5 | $\operatorname{AR}(0)-\operatorname{GARCH}(2,1)$ | 0.978 | 1.001 | 2.637 | 2.24 | 1 | 105 | 0.584 | 5.39 |
| GH-6 | $\operatorname{AR}(0)-\operatorname{GARCH}(2,1)$ | 0.982 | 0.997 | 2.595 | 1.50 | 1 | 83 | 0.563 | 4.02 |
| GH-7 | AR(1)-GARCH $(1,1)$ | 1.428 | 1.926 | 3.511 | 18.40 | 24 | 116 | 0.856 | 32.07 |
| GH-8 | AR(1)-GARCH $(1,2)$ | 1.356 | 1.747 | 3.298 | 12.58 | 20 | 110 | 0.841 | 29.49 |
| GH-9 | AR(1)-GARCH $(2,1)$ | 1.378 | 1.934 | 3.616 | 19.20 | 25 | 147 | 0.872 | 35.21 |
| GH-10 | MA(1)-GARCH $(1,1)$ | 0.911 | 1.376 | 2.769 | 36.44 | 25 | 521 | 0.949 | 64.54 |
| Code | Model | $\hat{s}_{1}$ | $\hat{s}_{2}$ | $\hat{d}$ | $z_{d}$ | $\hat{l}_{0.05}^{1}$ | $\hat{l}_{0.05}^{2}$ | $\hat{r}_{0.05}$ | $z_{r}$ |
| GH-1 | AR(0)-GARCH $(1,1)$ | -0.030 | -0.652 | -0.035 | -1.19 | 0.101 | 0.079 | 1.282 | 4.30 |
| GH-2 | $\operatorname{AR}(0)-\operatorname{GARCH}(1,1)$ | -0.080 | -0.076 | 0.004 | 0.17 | 0.098 | 0.081 | 1.202 | 4.08 |
| GH-3 | $\operatorname{AR}(0)-\operatorname{GARCH}(1,2)$ | -0.005 | 0.020 | 0.024 | 1.05 | 0.094 | 0.081 | 1.166 | 3.32 |
| GH-4 | $\operatorname{AR}(0)-\operatorname{GARCH}(1,2)$ | 0.020 | 0.026 | 0.007 | 0.27 | 0.108 | 0.093 | 1.151 | 1.68 |
| GH-5 | $\operatorname{AR}(0)-\operatorname{GARCH}(2,1)$ | -0.051 | 0.005 | 0.056 | 2.04 | 0.103 | 0.083 | 1.233 | 4.10 |
| GH-6 | $\operatorname{AR}(0)-\operatorname{GARCH}(2,1)$ | -0.044 | -0.012 | 0.032 | 1.23 | 0.097 | 0.083 | 1.178 | 3.50 |
| GH-7 | $\operatorname{AR}(1)-\operatorname{GARCH}(1,1)$ | 0.244 | 0.620 | 0.375 | 11.06 | 0.225 | 0.158 | 1.426 | 2.72 |
| GH-8 | AR(1)-GARCH $(1,2)$ | 0.231 | 0.614 | 0.383 | 14.52 | 0.201 | 0.143 | 1.405 | 2.59 |
| GH-9 | AR(1)-GARCH $(2,1)$ | 0.703 | 0.239 | 0.465 | 13.47 | 0.213 | 0.147 | 1.454 | 3.13 |
| GH-10 | MA(1)-GARCH $(1,1)$ | -0.476 | 1.034 | 1.509 | 29.43 | 0.070 | 0.081 | 0.867 | -3.90 |

Note: $\bar{\pi}^{1}, \bar{\pi}^{2}$ and $\bar{\pi}^{*}$ are the respective sample mean return of OGA, B\&H and the omniscient trader. $\tilde{\pi}$ is the exploitation ratio (Eq. (26)), and $\dot{\pi}$ is the relative superiority index (Eq. (27)). $\hat{p}_{w}$ is the sample winning probability of OGA over $\mathrm{B} \& \mathrm{H}$ (Eq. (28)). $\hat{s}_{1}$ and $\hat{s}_{2}$ are the corresponding sample Sharpe ratio of OGA and B\&H (Eq. (31)). Their sample difference is $\hat{d}$ (Eq. (32)). $\hat{l}_{0.05}^{1}$ and $\hat{l}_{0.05}^{2}$ are the sample luck coefficient of OGA and $\mathrm{B} \& \mathrm{H}$ (Eq. (39)), and $\hat{r}_{0.05}$ is the sample luck coefficient ratio between the two (Eq. (40)). The $z_{\pi}, z_{w}, z_{d}$ and $z_{r}$ are the test statistics of the mean return difference, winning probability, Sharpe ratio differential, and luck coefficient ratio, respectively. The critical value of them is 1.28 at the $10 \%$ significance level, and is 1.64 at the $5 \%$ significance level.
nonlinear processes AH-1 to AH-4, this dominance either disappears or becomes weaker. This can be easily shown by the sharp decline in the statistics $z_{p}, z_{w}$ and $z_{d}$ in Table 8 with an almost $0 \%$ exploitation ( $\tilde{\pi}$ ) of the maximum potential returns.

This discernible pattern also extends to Table 9. The double-digit $z_{p}, z_{w}$, and $z_{d}$ of the mixed processes (GH-7 to GH-10) distinguish themselves from the low, or even negative, single-digit ones of the pure nonlinear processes (GH-1 to GH-6). For the former, the GA has $84-95 \%$ chance of beating B\&H and earned 110-521\% more than $\mathrm{B} \& \mathrm{H}$. Again, from $z_{d}$, we know that the high returns are more than compensation for risk. Very similar to the case of ARCH, 20-25\% of the maximum potential returns can be exploited by the GA, but that value $\tilde{\pi}$ drops near to $0 \%$ when the underlying processes change to pure GARCH.

Despite the fact that pure nonlinear processes continue to deal the GA a hard blow, as far as the winning probability is concerned, its relative performance to $\mathrm{B} \& \mathrm{H}$ is overwhelmingly good. This can be reflected by the $z_{w}$ statistics which are consistently significantly positive in all cases. A similar property holds for the luck coefficient (see $z_{r}$ ). The only two exceptions are the cases AH-7 and GH-10, which, however, are not pure nonlinear. In fact, they both have $\mathrm{MA}(1)$ as their linear component.

### 6.4. Threshold Processes

The threshold process leads to a different kind of nonlinear process. While its global behavior is nonlinear, within each local territory, characterized by $\Omega_{i}$, it can be linear. TH-1 and TH-2 in Table 5 are exactly processes of this kind. The former is switching between two $\operatorname{AR}(1)$ processes, whereas the latter is switching between two ARMA $(1,1)$ processes. Since the GA can work well with linear processes, it would be interesting to know whether its effectiveness will extend to these local linear processes. Our results are shown in Table 10. The four statistics $z_{\pi}, z_{w}, z_{d}$, and $z_{r}$ all give positive results. The GA is seen to exploit $20-30 \%$ of the maximum potential returns, and the winning probabilities are greater than $90 \%$.

TH-4 and TH-5 are another kind of complication. TH-4 switches between two mixed processes, while TH-5 switches between a pure nonlinear process and a linear process. From previous experiences, we already knew that the GA can work well with the mixed process. Now, from Table 10, it seems clear that it can survive these two complications as well.

Finally, we come to the most difficult one TH-5, i.e the one which switches between two pure nonlinear (bilinear) processes. Since the GA did not show its competence in the pure nonlinear process, at least from the perspective of the return criteria, one may conjecture that TH-5 will deal another hard blow to the

Table 10. Performance Statistics of the OGA and B\&H - Threshold.

| Code | Model | $\bar{\pi}^{1}$ | $\bar{\pi}^{2}$ | $\bar{\pi}^{*}$ | $z_{\pi}$ | $\tilde{\pi}(\%)$ | $\dot{\pi}(\%)$ | $\hat{p}_{w}$ | $z_{w}$ |
| :--- | :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | ---: |
| TH-1 | TBL(2;1,0,0,0) | 0.612 | 1.233 | 3.372 | 24.89 | 23 | 160 | 0.910 | 45.30 |
| TH-2 | TBL(2;1,1,0,0) | 1.262 | 2.743 | 6.361 | 21.15 | 29 | 565 | 0.931 | 53.77 |
| TH-3 | TBL(2;0,0,1,1) | 1.161 | 1.074 | 4.207 | -4.38 | -3 | -54 | 0.502 | 0.13 |
| TH-4 | TBL(2;1,1,2,2) | 1.271 | 1.406 | 4.497 | 5.41 | 4 | 50 | 0.717 | 15.23 |
| TH-5 | TBL(2;2,0,2,2) | 0.654 | 1.236 | 3.890 | 37.38 | 18 | 168 | 0.919 | 48.56 |
| Code | Model | $\hat{s}_{1}$ | $\hat{s}_{2}$ | $\hat{d}$ | $z_{d}$ | $\hat{l}_{0.05}^{1}$ | $\hat{l}_{0.05}^{2}$ | $\hat{r}_{0.05}$ | $z_{r}$ |
| TH-1 | TBL(2;1,0,0,0) | -0.398 | 0.374 | 0.772 | 9.33 | 0.267 | 0.119 | 2.252 | 4.30 |
| TH-2 | TBL(2;1,1,0,0) | 0.093 | 0.727 | 0.634 | 11.86 | 0.329 | 0.163 | 2.012 | 2.95 |
| TH-3 | TBL(2;0,0,1,1) | 0.208 | 0.176 | -0.032 | -1.42 | 0.136 | 0.098 | 1.394 | 3.72 |
| TH-4 | TBL(2;1,1,2,2) | 0.208 | 0.426 | 0.219 | 10.41 | 0.192 | 0.140 | 1.379 | 2.97 |
| TH-5 | TBL(2;2,0,2,2) | -0.813 | 0.484 | 1.297 | 16.88 | 0.130 | 0.097 | 1.343 | 3.54 |

Note: $\bar{\pi}^{1}, \bar{\pi}^{2}$ and $\bar{\pi}^{*}$ are the respective sample mean return of OGA, B\&H and the omniscient trader. $\tilde{\pi}$ is the exploitation ratio (Eq. (26)), and $\dot{\pi}$ is the relative superiority index (Eq. (27)). $\hat{p}_{w}$ is the sample winning probability of OGA over B\&H (Eq. (28)). $\hat{s}_{1}$ and $\hat{s}_{2}$ are the corresponding sample Sharpe ratio of OGA and B\&H (Eq. (31)). Their sample difference is $\hat{d}$ (Eq. (32)). $\hat{l}_{0.05}^{1}$ and $\hat{l}_{0.05}^{2}$ are the sample luck coefficient of OGA and B\&H (Eq. (39)), and $\hat{r}_{0.05}$ is the sample luck coefficient ratio between the two (Eq. (40)). The $z_{\pi}, z_{w}, z_{d}$ and $z_{r}$ are the test statistics of the mean return difference, winning probability, Sharpe ratio differential, and luck coefficient ratio, respectively. The critical value of them is 1.28 at the $10 \%$ significance level, and is 1.64 at the 5\% significance level.

GA. Both $z_{p}$ and $z_{d}$ in Table 10 confirm this conjecture. Not just the returns, but $z_{w}$ shows that the winning probability is also not good, which is similar to what we experienced in BL-1 and BL-2. The only criterion that remains unaffected by this complication is the luck coefficient. Furthermore, it turns out that $z_{r}$ seems to give the most stable performance across all kinds of processes considered so far, except the MA process.

### 6.5. Chaotic Processes

Chaotic processes are also nonlinear, but they differ from the previous four nonlinear processes in that they are deterministic rather than stochastic. These processes can behave quite erratically without any discernible pattern. Can the GA survive well with this type of nonlinear process? The answer is a resounding yes. All the statistics in Table 11 are sending us this message.

The winning probabilities are all higher than $85 \%$. In the case of the Henon map (C-2), the GA even beats $\mathrm{B} \& \mathrm{H}$ in all of the 1000 trials. In addition, in this

Table 11. Performance Statistics of the OGA and B\&H - Chaos.

| Code | $\bar{\pi}^{1}$ | $\bar{\pi}^{2}$ | $\bar{\pi}^{*}$ | $z_{\pi}$ | $\tilde{\pi}(\%)$ | $\dot{\pi}(\%)$ | $\hat{p}_{w}$ | $z_{w}$ |
| :--- | ---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| C-1 | 1.019 | 5.664 | 21.876 | 31.15 | 22 | 24447 | 0.993 | 186.99 |
| C-2 | 5.387 | 23.235 | 33.452 | 85.62 | 64 | 407 | 1.000 | $*$ |
| C-3 | 0.937 | 4.124 | 11.374 | 44.65 | 31 | 5059 | 0.990 | 352.49 |
| C-4 | 1.188 | 3.066 | 25.563 | 22.91 | 8 | 999 | 0.950 | 65.29 |
| C-5 | 0.928 | 1.790 | 23.172 | 17.18 | 4 | 1197 | 0.876 | 36.08 |
| Code | $\hat{s}_{1}$ | $\hat{s}_{2}$ | $\hat{d}$ | $z_{d}$ | $\hat{l}_{0.05}^{1}$ | $\hat{l}_{0.05}^{2}$ | $\hat{r}_{0.05}$ | $z_{r}$ |
| C-1 | 0.009 | 0.832 | 0.824 | 16.59 | 0.297 | 0.184 | 1.615 | 2.28 |
| C-2 | 1.600 | 2.502 | 0.901 | 23.56 | 0.112 | 0.090 | 1.252 | 4.39 |
| C-3 | -0.075 | 1.160 | 1.235 | 28.92 | 0.153 | 0.127 | 1.207 | 2.75 |
| C-4 | 0.074 | 0.627 | 0.554 | 10.39 | 0.348 | 0.200 | 1.739 | 2.66 |
| C-5 | -0.045 | 0.518 | 0.563 | 14.45 | 0.279 | 0.169 | 1.649 | 2.88 |

Note: $\bar{\pi}^{1}, \bar{\pi}^{2}$ and $\bar{\pi}^{*}$ are the respective sample mean return of OGA, B\&H and the omniscient trader. $\tilde{\pi}$ is the exploitation ratio (Eq. (26)), and $\dot{\pi}$ is the relative superiority index (Eq. (27)). $\hat{p}_{w}$ is the sample winning probability of OGA over B\&H (Eq. (28)). $\hat{s}_{1}$ and $\hat{s}_{2}$ are the corresponding sample Sharpe ratio of OGA and B\&H (Eq. (31)). Their sample difference is $\hat{d}$ (Eq. (32)). $\hat{l}_{0.05}^{1}$ and $\hat{l}_{0.05}^{2}$ are the sample luck coefficient of OGA and B\&H (Eq. (39)), and $\hat{r}_{0.05}$ is the sample luck coefficient ratio between the two (Eq. (40)). The $z_{\pi}, z_{w}, z_{d}$ and $z_{r}$ are the test statistics of the mean return difference, winning probability, Sharpe ratio differential, and luck coefficient ratio, respectively. The critical value of them is 1.28 at the $10 \%$ significance level, and is 1.64 at the $5 \%$ significance level.
map, the GA is seen to exploited $64 \%$ of the potential excess returns earned by the omniscient trader, which is the highest of all the processes tested in this paper. One of the possible reasons why the GA can work well with these nonlinear deterministic processes is that they are not pure nonlinear. $\mathrm{C}-1, \mathrm{C}-2$ and $\mathrm{C}-4$ have linear $\mathrm{AR}(1)$ or $\mathrm{AR}(2)$ components. C-3, like the threshold processes, switches between two linear processes. As already evidenced in Section 6.4, the GA can handle these types of processes effectively. So, the success is not totally unanticipated.

However, the explanation above does not apply to C-5, which has no linear component. Nonetheless, statistics such as $z_{\pi}, \tilde{\pi}$ and $\hat{p}_{w}$ all indicate that this process is not as easy as the other four. For example, only $4 \%$ of the potential excess returns are exploited in this process. Regardless of these weaknesses, the fact that the GA can dominate $\mathrm{B} \& \mathrm{H}$ in this case motivates us to ask the following question: Can the GA work better for the pure nonlinear deterministic processes than the respective stochastic ones, and hence can it help distinguish the chaotic processes from the stochastic processes? This is a question to pursue in the future.

### 6.6. Summary

The Monte Carlo simulation analysis conducted above provides us with an underpinning of the practical financial applications of the GA. It pinpoints the kinds of stochastic processes which we may like to see fruitful results. We have found that the GA can perform well with all kinds of stochastic processes which have a linear process (signal) as a part of them. Preliminary studies also suggest that it may also work well with chaotic processes. However, the class of nonlinear stochastic processes presents a severe limitation for the GA. In the next section, we shall see the empirical relevance of these results by actually applying OGA-based trading strategies to financial data.

## 7. EMPIRICAL ANALYSIS

### 7.1. Data Description and Analysis

The empirical counterpart of this paper is based on two sets of high-frequency time series data regarding foreign exchange rates, namely, the Euro dollar vs. the U.S. dollar $E U R / U S D$ and the U.S. dollar vs. the Japanese yen $U S D / J P Y .^{6}$ The data is from January 11, 1999 to April 17, 1999. Data within this period are further divided into 12 sub-periods with roughly equal numbers of observations. Table 12 gives the details.

Let $P_{i, t}^{U}\left(P_{i, t}^{P}\right)$ denote the $t$-th $\left(t=1,2, \ldots, n_{i}\right)$ observation of the $i$ th sub-period ( $i=A, B, \ldots, L$ ) of the EUR/USD (USD/JPY) forex series. The price series is transformed into the return series by the usual logarithmic formulation,

$$
\begin{equation*}
r_{i, t}^{j}=\ln \left(P_{i, t}^{j}\right)-\ln \left(P_{i, t-1}^{j}\right) \tag{47}
\end{equation*}
$$

where $j=U, P$. Tables 13 and 14 give some basic statistics of the returns of each sub-period.

Both return series share some common features. From Tables 13 and 14, the mean, median and skewness of these two return series are all close to zero. The kurtosis is much higher than 3, featuring the well-known fat-tail property. The Jarque-Bera (1980) test further confirms that these forex returns do not follow the normal distribution, and that is true for each sub-period. In addition, the series is not independent due to its significant negative first-order serial correlation $\rho_{1}$. However, there is no evidence of serial correlation in higher orders. ${ }^{7}$

To apply what we learned from the Monte Carlo simulation to predict the effectiveness of the GA over these series, we must first gauge their likely stochastic processes. Here we follow a standard procedure frequently used in econometrics

Table 12. Data Quotations - EUR/USD and USD/JPY.

| Sub-Period | A | B | C | D | E | F |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| EUR/USD |  |  |  |  |  |  |
| Number | 12000 | 12000 | 12000 | 12000 | 12000 | 12000 |
| From (GMT) | 2/25 7:59 | 3/1 0:59 | 3/3 15:36 | 3/8 6:43 | 3/10 6:53 | 3/12 7:26 |
| To (GMT) | 2/26 8:22 | 3/2 7:17 | 3/5 3:04 | 3/9 1:08 | 3/11 7:12 | 3/15 1:16 |
| Sub-Period | G | H | I | J | K | L |
| Number | 12000 | 12000 | 12000 | 12000 | 12000 | 12000 |
| From (GMT) | 3/17 7:36 | 3/19 0:19 | 3/24 15:06 | 3/26 15:46 | 3/31 7:32 | 4/15 6:14 |
| To (GMT) | 3/18 6:12 | 3/22 2:01 | 3/26 2:12 | 3/30 6:23 | 4/02 1:14 | 4/17 0:37 |
| Sub-Period | A | B | C | D | E | F |
| USD/JPY |  |  |  |  |  |  |
| Number | 12000 | 12000 | 12000 | 12000 | 12000 | 10808 |
| From (GMT) | 1/11 6:11 | 1/15 0:00 | 1/27 15:14 | 2/04 8:47 | 2/17 7:20 | 2/23 6:10 |
| To (GMT) | 1/14 8:11 | 1/21 0:00 | 2/03 3:24 | 2/11 2:43 | 2/23 6:09 | 2/26 21:48 |
| Sub-Period | G | H | I | J | K | L |
| Number | 12000 | 12000 | 11026 | 12000 | 12000 | 12000 |
| From (GMT) | 2/28 18:15 | 3/04 10:02 | 3/09 21:52 | 3/15 5:25 | 3/18 6:07 | 3/24 13:00 |
| To (GMT) | 3/04 10:01 | 3/09 21:52 | 3/15 1:21 | 3/18 6:06 | 3/24 13:00 | 3/30 10:41 |

Note: GMT: Greenwich Mean Time.
(Chen \& Lu, 1999). First, notice that all series used in our Monte Carlo simulation are stationary. To make sure that the forex returns are stationary, the Augmented Dickey-Fuller (ADF) test is applied (Dickey \& Fuller, 1979). From Table 15, the null hypothesis that $r_{i, t}^{j}$ contains a unit root is rejected at the $1 \%$ significance level, meaning that the $r_{i, t}^{j}$ are stationary.

Second, since our Monte Carlo simulations demonstrate the effectiveness of the GA over the linear stochastic processes, it is important to know whether the forex returns have a linear component. To do so, the famous Rissanen's predictive stochastic complexity (PSC) as a linear filter is taken. ${ }^{8}$ Table 15 gives the ARMA $(p, q)$ process extracted from the forex return series. A MA(1) linear process is founded for both forex returns in each sub-period. In fact, it re-confirms the early finding that the high-frequency forex returns follow a MA(1) process (Moody \& Wu, 1997; Zhou, 1996).

Third, it should be not surprising if none of these series is just linear. To see whether nonlinear dependence exists, one of the most frequently used statistics, the $B D S$ test, is applied to the residuals filtered through the PSC filter. ${ }^{9}$ There

Table 13. Basic Statistics of the Return Series - EUR/USD.

| Sub-Period | A | B | C | D | E | F |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Mean | $-2.56 \mathrm{E}-07$ | $-8.13 \mathrm{E}-07$ | $-7.37 \mathrm{E}-07$ | $5.39 \mathrm{E}-07$ | $5.63 \mathrm{E}-07$ | $-7.49 \mathrm{E}-07$ |
| Median | 0.000000 | 0.000000 | 0.000000 | 0.000000 | 0.000000 | 0.000000 |
| Std. Dev. | 0.000252 | 0.000252 | 0.000213 | 0.000191 | 0.000238 | 0.000264 |
| Skewness | -0.015831 | 0.007214 | -0.034436 | 0.002017 | -0.001071 | -0.009908 |
| Kurtosis | 5.606484 | 5.558600 | 5.636056 | 5.976148 | 6.136196 | 5.757020 |
| Jarque-Bera | 3397.10 | 3273.05 | 3476.48 | 4428.37 | 4917.45 | 3800.46 |
| $P$-value | 0.000000 | 0.000000 | 0.000000 | 0.000000 | 0.000000 | 0.000000 |
| $\rho_{1}$ | -0.513935 | -0.503725 | -0.494695 | -0.504014 | -0.486925 | -0.509612 |
|  |  |  |  |  |  |  |
| Sub-Period | G | H | I | K |  |  |
| Mean | $3.81 \mathrm{E}-07$ | $-8.00 \mathrm{E}-07$ | $-7.48 \mathrm{E}-07$ | $-5.64 \mathrm{E}-08$ | $2.37 \mathrm{E}-07$ | $-1.13 \mathrm{E}-06$ |
| Median | 0.000000 | 0.000000 | 0.000000 | 0.000000 | 0.000000 | 0.000000 |
| Std. Dev. | 0.000225 | 0.000217 | 0.000184 | 0.000241 | 0.000292 | 0.000219 |
| Skewness | 0.011155 | -0.050369 | -0.119412 | 0.007646 | -0.021431 | -0.203838 |
| Kurtosis | 6.512019 | 5.435495 | 6.226714 | 5.337107 | 8.780986 | 10.97326 |
| Jarque-Bera | 616.88 | 2970.40 | 5233.92 | 2730.92 | 16708.03 | 31861.55 |
| $P$-value | 0.000000 | 0.000000 | 0.000000 | 0.000000 | 0.000000 | 0.000000 |
| $\rho_{1}$ | -0.493223 | -0.505528 | -0.480500 | -0.498232 | -0.475452 | -0.464571 |

Note: $\rho_{1}$ is the first-order autocorrelation coefficient. Jarque-Bera statistic converges to a chi-square distribution with two degrees of freedom under the normality assumption.

Table 14. Basic Statistics of the Return Series - USD/JPY.

| Sub-Period | A | B | C | D | E | F |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Mean | $3.97 \mathrm{E}-07$ | $-5.16 \mathrm{E}-07$ | $-2.01 \mathrm{E}-06$ | $2.54 \mathrm{E}-07$ | $1.69 \mathrm{E}-06$ | $-1.44 \mathrm{E}-06$ |
| Median | 0.000000 | 0.000000 | 0.000000 | 0.000000 | 0.000000 | 0.000000 |
| Std. Dev. | 0.000413 | 0.002108 | 0.001853 | 0.000332 | 0.000311 | 0.000363 |
| Skewness | 0.008135 | 0.080038 | -0.018340 | -0.057694 | 0.022959 | -0.003358 |
| Kurtosis | 6.769064 | 6.711594 | 6.854310 | 7.170642 | 6.757800 | 6.374525 |
| Jarque-Bera | 7091.806 | 6898.478 | 7426.049 | 8700.883 | 7059.230 | 5123.885 |
| $P$-value | 0.000000 | 0.000000 | 0.000000 | 0.000000 | 0.000000 | 0.000000 |
| $\rho_{1}$ | -0.343317 | -0.338790 | -0.370748 | -0.362052 | -0.360786 | -0.335953 |
|  |  |  |  |  |  |  |
| Sub-Period | G | H | J | K |  |  |
| Mean | $2.53 \mathrm{E}-06$ | $-1.09 \mathrm{E}-06$ | $-2.54 \mathrm{E}-06$ | $-2.75 \mathrm{E}-07$ | $-7.87 \mathrm{E}-07$ | $1.90 \mathrm{E}-06$ |
| Median | 0.000000 | 0.000000 | 0.000000 | 0.000000 | 0.000000 | 0.000000 |
| Std. Dev. | 0.000301 | 0.000279 | 0.000322 | 0.000287 | 0.000265 | 0.000247 |
| Skewness | 0.080100 | 0.019734 | 0.079313 | 0.002414 | -0.019244 | 0.213584 |
| Kurtosis | 5.597214 | 6.763973 | 6.747828 | 8.198238 | 7.650768 | 6.701801 |
| Jarque-Bera | 338.029 | 7083.936 | 6459.934 | 13508.60 | 10811.96 | 6941.746 |
| $P$-value | 0.000000 | 0.000000 | 0.000000 | 0.000000 | 0.000000 | 0.000000 |
| $\rho_{1}$ | -0.436860 | -0.396329 | -0.344660 | -0.348622 | -0.361993 | -0.364189 |

Note: $\rho_{1}$ is the first-order autocorrelation coefficient. Jarque-Bera statistic converges to a chi-square distribution with two degrees of freedom under the normality assumption.

Table 15. Basic Econometric Properties of the Return Series - EUR/USD and USD/JPY.

| Sub-Period | A | B | C | D | E | F |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| EUR/USD |  |  |  |  |  |  |
| ADF | -74.9502 | -76.4264 | -74.0755 | -76.6226 | -77.4292 | -79.1714 |
| Critical Value PSC | -3.4341 | -3.4341 | -3.4341 | -3.4341 | -3.4341 | -3.4341 |
|  | $(0,1)$ | $(0,1)$ | $(0,1)$ | $(0,1)$ | $(0,1)$ | $(0,1)$ |
|  | G | H | I | J | K | L |
| ADF <br> Critical Value PSC | -74.7427 | -74.7053 | -68.8254 | -73.4958 | -72.3726 | -67.6148 |
|  | -3.4341 | -3.4341 | -3.4341 | -3.4341 | -3.4341 | -3.4341 |
|  | $(0,1)$ | $(0,1)$ | $(0,1)$ | $(0,1)$ | $(0,1)$ | (0.1) |
|  | A | B | C | D | E | F |
| USD/JPY |  |  |  |  |  |  |
| ADF | -57.1573 | -55.2394 | -56.0518 | -56.8433 | -55.0202 | -51.1507 |
| Critical Value | -2.5660 | -2.5660 | -2.5660 | -3.4341 | -3.4341 | -3.4342 |
| PSC | $(0,1)$ | $(0,1)$ | $(0,1)$ | $(0,1)$ | $(0,1)$ | $(0,1)$ |
|  | G | H | I | J | K | L |
| ADF | -59.3422 | -57.4123 | -55.5809 | -58.0822 | -57.5485 | -59.5623 |
| Critical Value | -3.4341 | -3.4341 | -3.4341 | -3.4341 | -3.4341 | -3.4341 |
| PSC | $(0,1)$ | $(0,1)$ | $(0,1)$ | $(0,1)$ | $(0,1)$ | (0.1) |

Note: The "Critical Value" indicates the critical value of the ADF test that is taken from the table provided by Dickey and Fuller at the $1 \%$ significance level.
are two parameters used to conduct the BDS test. One is the distance measure (standard deviations), and the other is the embedding dimension. The parameter " $\varepsilon$ " considered here is equal to one standard deviation. (In fact, other are also tried, but the results are not sensitive to the choice of $\varepsilon$.) The embedding dimensions considered range from 2 to 5 . Following Barnett et al. (1997), if the absolute values of all BDS statistics under various embedding dimensions are greater than 1.96, the null hypothesis of an identical independent distribution (IID) is rejected. From Table 16, the BDS statistics for the EUR/USD and USD/JPY are all large enough to reject the null hypothesis, i.e. nonlinear dependence is detected.

Fourth, given the existence of the nonlinear dependence, the next step is to identify its possible form, i.e. by modeling nonlinearity. While there is no standard answer as to how this can be done, the voluminous (G)ARCH literature over the past two decades has proposed a second-moment connection (Bollerslev et al., 1992). In order to see whether (G)ARCH can successfully capture nonlinear signals, we

Table 16. The BDS Test of the PSC-filtered Return Series - EUR/USD and USD/JPY.

| Sub-Period <br> Part | A |  | B |  | C |  | D |  | E |  | F |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | I | II | I | II | I | II | I | II | I | II | I | II |
| EUR/USD |  |  |  |  |  |  |  |  |  |  |  |  |
| DIM $=2$ | 20.47 | 26.82 | 22.58 | 26.56 | 13.60 | 20.25 | 17.15 | 14.66 | 18.23 | 18.09 | 18.03 | 19.37 |
| DIM $=3$ | 27.57 | 34.17 | 30.61 | 34.72 | 19.44 | 26.84 | 22.50 | 20.12 | 22.78 | 23.48 | 24.63 | 26.43 |
| DIM $=4$ | 33.60 | 40.03 | 37.25 | 40.81 | 23.80 | 31.27 | 26.80 | 24.22 | 25.68 | 27.63 | 30.21 | 32.09 |
| DIM $=5$ | 38.50 | 45.80 | 43.40 | 46.75 | 27.43 | 35.23 | 30.38 | 27.40 | 28.54 | 31.23 | 35.26 | 37.94 |
|  | G |  | H |  | I |  | J |  | K |  | L |  |
|  | I | II | I | II | I | II | I | II | I | II | I | II |
| DIM $=2$ | 12.04 | 16.97 | 23.90 | 19.45 | 13.06 | 12.40 | 20.13 | 13.41 | 35.69 | 19.74 | 8.18 | 22.23 |
| DIM $=3$ | 17.84 | 22.20 | 30.02 | 25.59 | 17.30 | 17.31 | 26.84 | 18.79 | 46.83 | 24.39 | 10.98 | 27.08 |
| DIM $=4$ | 21.09 | 26.34 | 34.39 | 30.41 | 20.35 | 20.57 | 31.24 | 22.98 | 56.42 | 27.22 | 12.97 | 30.22 |
| DIM $=5$ | 24.08 | 30.18 | 39.31 | 35.47 | 23.29 | 23.40 | 35.39 | 26.48 | 66.58 | 29.79 | 14.20 | 33.13 |


|  | A |  | B |  | C |  | D |  | E |  | F |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | I | II | I | II | I | II | I | II | I | II | I | II |
| USD/JPY |  |  |  |  |  |  |  |  |  |  |  |  |
| DIM $=2$ | 15.36 | 23.15 | 15.68 | 13.41 | 12.00 | 16.63 | 14.76 | 20.44 | 12.98 | 17.84 | 17.88 | 16.61 |
| DIM $=3$ | 17.89 | 28.38 | 18.83 | 16.04 | 14.54 | 20.02 | 17.11 | 23.15 | 16.08 | 20.87 | 21.35 | 18.94 |
| DIM $=4$ | 20.03 | 31.37 | 20.17 | 17.89 | 15.32 | 22.24 | 18.72 | 24.27 | 17.49 | 22.82 | 23.35 | 20.44 |
| DIM $=5$ | 22.30 | 34.58 | 21.57 | 19.13 | 16.07 | 24.42 | 20.28 | 25.43 | 18.52 | 24.56 | 24.43 | 22.16 |
|  | G |  | H |  | I |  | J |  | K |  | L |  |
|  | I | II | I | II | I | II | I | II | I | II | I | II |
| DIM $=2$ | 15.65 | 11.34 | 15.56 | 16.84 | 16.44 | 15.51 | 20.98 | 17.79 | 19.41 | 15.51 | 15.28 | 15.61 |
| DIM $=3$ | 17.64 | 13.92 | 18.57 | 18.91 | 18.50 | 18.68 | 25.07 | 21.84 | 21.94 | 16.84 | 16.32 | 17.87 |
| DIM $=4$ | 19.30 | 15.35 | 20.86 | 19.45 | 19.78 | 21.02 | 27.72 | 24.43 | 23.23 | 17.52 | 17.21 | 19.34 |
| DIM $=5$ | 20.82 | 16.49 | 23.10 | 19.73 | 20.95 | 22.76 | 30.10 | 26.45 | 24.15 | 18.56 | 18.14 | 20.62 |

Note: Due to the size of the data which is beyond the affordable limit of the software computing the BDS statistics, each sub-period was divided into two parts before the BDS test was applied. The BDS statistic follows an asymptotically standard normal distribution.
carry out the Lagrange Multiplier (LM) test for the presence of ARCH effects. The LM test for ARCH effects is a test based on the following model:

$$
\begin{equation*}
\sigma_{t}^{2}=h\left(\alpha_{0}+\alpha_{1} \varepsilon_{t-1}^{2}+\ldots+\alpha_{p} \varepsilon_{t-p}^{2}\right) \tag{48}
\end{equation*}
$$

where $h$ is a differential function. The null hypothesis that the ARCH effect does not exist is

$$
\begin{equation*}
\alpha_{1}=\ldots=\alpha_{p}=0 \tag{49}
\end{equation*}
$$

By taking $p=1,2, \ldots, 4$, the LM test results are given in Table 17. It is found that the ARCH effect does exist in both return series.

Table 17. The LM Test of the ARCH Effect in the Return Series - EUR/USD and USD/JPY.

| Sub-Period | A | B | C | D | E | F |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| EUR/USD |  |  |  |  |  |  |
| $p=1$ | 1029.94 | 821.665 | 681.92 | 560.27 | 463.98 | 401.08 |
| $p=2$ | 1572.34 | 1191.26 | 998.22 | 1094.72 | 960.83 | 585.88 |
| $p=3$ | 2030.32 | 1501.74 | 1202.15 | 1320.58 | 1052.54 | 705.17 |
| $p=4$ | 2169.98 | 1731.33 | 1295.77 | 1471.40 | 1195.93 | 871.73 |
| Sub-Period | G | H | I | J | K | L |
| $p=1$ | 275.07 | 797.26 | 411.61 | 390.94 | 1584.30 | 1571.04 |
| $p=2$ | 423.33 | 1168.19 | 689.02 | 553.11 | 1668.88 | 1587.53 |
| $p=3$ | 493.11 | 1262.87 | 1001.22 | 678.90 | 1714.39 | 1640.60 |
| $p=4$ | 551.99 | 1354.28 | 1050.53 | 715.68 | 2036.42 | 1641.41 |
| Sub-Period | A |  | B | C | D |  |
| USD/JPY |  |  |  | E |  | F |
| $p=1$ | 533.15 | 411.35 | 479.80 | 769.49 | 550.15 | 685.34 |
| $p=2$ | 639.75 | 490.58 | 6018.02 | 849.31 | 604.18 | 752.71 |
| $p=3$ | 677.49 | 531.78 | 667.50 | 854.11 | 614.26 | 821.85 |
| $p=4$ | 709.00 | 559.97 | 687.09 | 923.01 | 636.99 | 854.71 |
| Sub-Period | G | H | I | J | K | L |
| $p=1$ | 600.528 | 545.791 | 696.185 | 749.650 | 883.107 | 795.762 |
| $p=2$ | 648.101 | 656.653 | 758.918 | 1094.82 | 926.127 | 929.618 |
| $p=3$ | 695.639 | 727.043 | 811.000 | 1101.78 | 939.221 | 1059.00 |
| $p=4$ | 726.942 | 764.836 | 844.766 | 1103.08 | 951.489 | 1109.23 |

Note: The LM test is asymptotically distributed as $\chi^{2}$ with $p$ degrees of freedom when the null hypothesis is true. There is no need to report the p values here because they are all 0.0000 .

After these series of statistical tests, we may conclude that basically both the $E U R / U S D$ and the USD/JPY return series have MA(1) as a linear component and ARCH as a part of its nonlinear components. In Section 6.3, the Monte Carlo simulation analysis already indicated that the GA can work well with MA(1) plus (G)ARCH processes. To see the empirical relevance of the simulation study, in the next sections, the GA is applied to the two return series.

### 7.2. Experimental Design

In order to compare the empirical results with our earlier simulation analysis, the experiments are designed in a similar fashion to the one which our Monte Carlo
simulation follows. Specifically, many "ensembles" are generated from the original series to evaluate the performance of the GA. Of course, rigorously speaking, they are not the "ensembles" defined in the stochastic process. They are just subseries taken from the original return series. Each subseries has 105 observations. The first 70 observations are treated as the training sample, and the last 35 observations are used as the testing sample.

Nonetheless, to make the tests we developed in Section 4 applicable, we cannot just continuously chop the return series into subseries, because doing so will not make the sampling process independent, and hence will violate the fundamental assumption required for the central limit theorem. One solution to this problem is to leave an interval between any two consecutive subseries so that they are not immediately connected. The purpose in doing this is hopefully to make them independent of each other as if they were sampled independently. However, how large an interval would suffice? To answer this question, we take a subsequence with a fixed number of lags, say, $\left\{r_{i, t}^{j}, r_{i, t+k}^{j}, r_{i, t+2 k}^{j}, \ldots\right\}$ from the original return series, where $k$ varies from $40,60, \ldots$, to 300 . We then apply the BDS test to each of these subsequences.

Table 18 summarizes the BDS test results. For the EUR/USD case, it is found that when $k$ is greater than 100, the null hypothesis that the subsequence $\left\{r_{i, t}^{j}, r_{i, t+k}^{j}, r_{i, t+2 k}^{j}, \ldots\right\}$ is IID is not rejected. In other words, leaving an interval of 100 observations between each of two consecutive subseries would suffice. For the EUR/USD case, $k$ can even be smaller than 60 . To ensure the quality of the sampling process, we, however, take an even larger number of lags, i.e. $k=200$. This choice leaves us with a total of 720 subseries from the EUR/USD and 709 subseries from the USD/JPY.

The GA is then employed to extract trading strategies from the training samples of these subseries, and the strategies extracted are further applied to the respective testing samples. The resulting accumulated returns $(p)$ are then compared with that of the B\&H strategy.

### 7.3. Results of the Experiments

Since the analysis of the data shows that the two forex returns are mixtures of MA(1) and (G)ARCH processes, our previous results of Monte Carlo simulations may provide a good reference for what one can expect from such empirical applications. Both Tables 8 and 9 indicate the superior performance of the GA over $\mathrm{B} \& \mathrm{H}$, except in relation to the criterion for the luck coefficient, when the underlying stochastic processes are MA plus (G)ARCH. Will the dominance carry over?


Table 18. The BDS Test of the Lag Period in the Return Series - EUR/USD and USD/JPY.

Note: The BDS statistic follows an asymptotically standard normal distribution.

Table 19 is the kind of table which we have presented many times in Section 6. All the key statistics $z_{p}, z_{w}$, and $z_{d}$ are consistent with those of AH-7 (Table 8) and GH-10 (Table 9). So, in both forex return series, the dominance of the GA over B\&H is statistically significant. The consistency continues even to a finer level of the results: $\bar{\pi}^{1}<1$ and $\bar{\pi}^{2}>1$. As already seen, $B \& H$ earned negative profits in both of the cases AH-7 and GH-10, while the GA earned positive profits in both cases. In addition, both the winning probability and the exploitation ratio are also

Table 19. Performance Statistics of the OGA and B\&H - EUR/USD and USD/JPY.

|  | $\bar{\pi}^{1}$ | $\bar{\pi}^{2}$ | $\bar{\pi}^{*}$ | $z_{\pi}$ | $\tilde{\pi}(\%)$ | $\dot{\pi}(\%)$ | $\hat{p}_{w}$ | $z_{w}$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| EUR/USD | 0.9999 | 1.0012 | 1.0028 | 38.58 | 43 | 9257 | 0.972 | 77.10 |
| USD/JPY | 0.9999 | 1.0010 | 1.0039 | 23.70 | 27 | 11462 | 0.850 | 26.17 |
|  | $\hat{s}_{1}$ | $\hat{s}_{2}$ | $\hat{d}$ | $z_{d}$ | $\hat{l}_{0.05}^{1}$ | $\hat{l}_{0.05}^{2}$ | $\hat{r}_{0.05}$ | $z_{r}$ |
| EUR/USD | -0.0338 | 1.4193 | 1.4532 | 18.32 | 0.0812 | 0.0933 | 0.8710 | -1.69 |
| USD/JPY | -0.0086 | 0.8786 | 0.8873 | 20.64 | 0.0826 | 0.0948 | 0.8713 | -1.66 |

Note: $\bar{\pi}^{1}, \bar{\pi}^{2}$ and $\bar{\pi}^{*}$ are the respective sample mean return of OGA, B\&H and the omniscient trader. $\tilde{\pi}$ is the exploitation ratio (Eq. (26)), and $\pi$ is the relative superiority index (Eq. (27)). $\hat{p}_{w}$ is the sample winning probability of OGA over B\&H (Eq. (28)). $\hat{s}_{1}$ and $\hat{s}_{2}$ are the corresponding sample Sharpe ratio of OGA and B\&H (Eq. (31)). Their sample difference is $\hat{d}$ (Eq. (32)). $\hat{l}_{0.05}^{1}$ and $\hat{l}_{0.05}^{2}$ are the sample luck coefficient of OGA and B\&H (Eq. (39)), and $\hat{r}_{0.05}$ is the sample luck coefficient ratio between the two (Eq. (40)). The $z_{\pi}, z_{w}, z_{d}$ and $z_{r}$ are the test statistics of the mean return difference, winning probability, Sharpe ratio differential, and luck coefficient ratio, respectively. The critical value of them is 1.28 at the $10 \%$ significance level, and is 1.64 at the $5 \%$ significance level.
comparable. $\hat{p}_{w}$ is around $95 \%$ for both AH-7 and GH-10, and $\tilde{\pi}$ is about $25 \%$. The value of $\hat{p}_{w}$ remains as high for the EUR/USD series, while it drops a little to $85 \%$ for the USD/JPY series. As to $\tilde{\pi}$, it is also about $25 \%$ for the USD/JPY series, but is greater than $40 \%$ for the EUR/USD series.

Notice that our earlier simulation result already indicated that, for some reason unknown to us, the MA component when combined with the ARCH or GARCH component may bring a negative impact to the luck coefficient. This has been already shown in the cases AH-7 and GH-10. What interests us here is that this observation repeats itself in our empirical results. The statistic $z_{r}$ is statistically negative in both return series. As a result, to a large extent, what we have found from the early Monte Carlo simulations applies quite well to the real data. Hence, the GA can be useful in extracting information to develop trading strategies involving these high-frequency financial data because the underlying stochastic process, based on the Monte Carlo simulation analysis, is not a hard one for the GA.

## 8. CONCLUDING REMARKS

The literature on financial data mining, driven by the rapid development and applications of computational intelligence tools, are frequently clothed with a "magic house" notoriety. Unlike in mainstream econometrics, users are usually
not well informed of the stochastic properties of these tools, which in turn makes it difficult to grasp the significance of the result obtained from one specific application, be it positive or negative. An essential question is how we can know that what happens in one specific application can or cannot extend to the other one. Will we still be so "lucky" next time?

By using the Monte Carlo simulation methodology, a statistical foundation for using the GA in market-timing strategies is initiated. This foundation would allow us to evaluate how likely the GA will work given a time series whose underlying stochastic process is known. This helps us to distinguish the luck from normal expectations. We believe that this is a major step toward lightening the black box. We emphasize that this work provides $a$ statistical foundation, not the statistical foundation, because there are many other ways of enriching the current framework and of making it more empirically relevant.

First, different benchmarks may replace the B\&H strategy. This is particularly so given a series of articles showing that simple technical analysis can beat $\mathrm{B} \& \mathrm{H}$. However, since we can never run out of interesting benchmarks, the exploitation ratio $\tilde{\pi}$ introduced in this paper will always be a good reference. For example, in this paper, we can hardly have a $\tilde{\pi}$ of $30 \%$ or higher. Consequently, the $70 \%$ left there may motivate us to try more advanced version of the GA or different computational intelligence algorithms.

Second, financial time series are not just restricted to the six stochastic processes considered in this paper, but introducing new stochastic processes causes no problems for the current framework. Third, different motivations may define different evaluation criteria. The four criteria used in this paper are by no means exhausted. For example, the downside risk or VaR (Value at Risk) frequently used in current risk management can be another interesting criterion. However, again, it is straightforward to add more criteria to the current framework as long as one is not bothered by deriving the corresponding statistical tests. Fourth, the focus of this paper is to initiate a statistical foundation. Little has been addressed regarding the practical trading behavior or constraints. Things like transaction costs, non-synchronous trading, etc., can be introduced to this framework quite easily. Fifth, our framework is also not restricted to just the ordinary GA, for the general methodology applies to other machine learning tools, including the more advanced versions of the GA.

Finally, while, in this paper, we are only interested in the statistical foundation, we do not exclude the possibilities of having other foundations. As a matter of fact, we believe that a firm statistical foundation can show us where to ask the crucial questions, and that will help build a more general mathematical foundation. For example, in this paper, we have been already well motivated by the question as to why the GA performed quite poorly in the pure nonlinear stochastic processes, but
performed well in the chaotic processes. Of course, this statistical finding alone may need more work before coming to its maturity. However, the point here is that theoretical questions regarding the GA's performance cannot be meaningfully answered unless we have firmly grasped their behavior in a statistical way.

## NOTES

1. The interested reader can obtain more spread applications in the fields of research from Goldberg (1989).
2. A bibliographic list of financial applications of genetic algorithms and genetic programming can be found in Chen and Kuo (2002) and Chen and Kuo (2003). For a general coverage of this subject, interested readers are referred to Chen (1998a), Chen (2002) and Chen and Wang (2003). As opposed to the conventional technical analysis, the advantages of using GAs and GP are well discussed in Allen and Karjalainen (1999), and is also briefly reviewed in another paper of this special issue. (Yu et al., 2004).
3. For example, Chen (1998b) sorted out three stochastic properties which may impinge upon the performance of GAs in financial data mining. These are the no-free-lunch property, the well-ordered property and the existence of temporal correlation. Several tests of these properties are then proposed and an a priori evaluation of the potential of GAs can be made based on these proposed tests.
4. $\bar{\pi}^{*}$ is a sample average of $\pi_{i}^{*}$, which is the accumulated return earned by the omniscient trader in the $i$ th ensemble of the Monte Carlo simulation.
5. Doing this enables us to apply the central limit theorem to derive the asymptotic distribution of the various test statistics mentioned in Section 4.
6. The main source of this dataset is the interbank spot prices published by Dow Jones in a multiple contributors page (the TELERATE page). This covers markets worldwide 24 hours a day. These prices are quotations of the average prices of bid and ask and not actual trading prices. Furthermore, they are irregularly sampled and therefore termed as tick-by-tick prices.
7. The clear cut-off pattern appearing at the first lag suggests that these series involve a MA(1) process. Later on, from more rigorous statistics, we will see that indeed it is the case.
8. The detailed description can be found in Chen and Tan (1996).
9. Once the linear signals are filtered out, any signals left in the residual series must be nonlinear. "BDS" stands for "Brock, Dechert and Scheinkman" see Brock et al. (1996).

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## APPENDIX A

## A.1. Coding Trading Strategies

Based on the trading formulation (3), to encode a trading strategy, we only need to encode the CONDS with three primitive predicates, which means the following three parts:

- $\vec{a}=\left(a_{1}, a_{2}, a_{3}\right)$,
- $\vec{\oplus}=\left(\oplus_{1}, \oplus_{2}, \oplus_{3}\right)$,
- the logical combination of the three predicates $\operatorname{Cond}\left(r_{t-i}\right)(i=1,2,3)$.

To encode $\vec{a}$, we first transform the range of the variable $Z\left[Z_{\min }, Z_{\max }\right]$ into a fixed interval, say $[0,31]$.

$$
\begin{equation*}
Z^{*}=\frac{Z-Z_{\min }}{Z_{\max }-Z_{\min }} \times 32 \tag{A.1}
\end{equation*}
$$

Then $Z^{*}$ will be further transformed by Eq. (A.2).

$$
Z^{* *}= \begin{cases}n, & \text { if } n \leq Z^{*}<n+1  \tag{A.2}\\ 31 & \text { if } Z^{*}=32\end{cases}
$$

Since there are only 32 cutoff values, each $a_{i}$ can be encoded by a 5 -bit string. Hence the vector $\vec{a}$ can be encoded by a 15 -bit binary string. To encode $\vec{\oplus}$, notice that each $\oplus$ has only two possibilities: $\geq$ or $<$. Therefore, a $\vec{\oplus}$ can be encoded by a 3-bit binary string (Table A.1). Finally, there are a total of totally 8 logical combinations for three predicates and they can be encoded by 3-bit strings (Table A.2).

In sum, a CONDS can be encoded by a 21-bit string ( 3 for logical combinations, 3 for inequalities, and 15 for the three thresholds). Therefore, each trading strategy can be represented by a 21-bit string.

Table A.1. Binary Codes for Inequality Relation.

| Code | $\oplus_{1}$ | $\oplus_{2}$ | $\oplus_{3}$ |
| :--- | :--- | :--- | :--- |
| $0(000)$ | $\geq$ | $\geq$ | $\geq$ |
| $1(001)$ | $<$ | $\geq$ | $\geq$ |
| $2(010)$ | $\geq$ | $<$ | $\geq$ |
| $3(011)$ | $\geq$ | $\geq$ | $<$ |
| $4(100)$ | $<$ | $\geq$ | $<$ |
| $5(101)$ | $<$ | $<$ | $<$ |
| $6(110)$ | $\geq$ | $<$ | $<$ |
| $7(111)$ | $<$ |  | $\geq$ |

Table A.2. Binary Codes for Logical Combinations.

| Logic Code | Logical Combination of Predicates |
| :--- | :--- |
| $0(000)$ | Cond 1 OR (Cond 2 AND Cond 3) |
| $1(001)$ | Cond 1 AND (Cond 2 OR Cond 3) |
| $2(010)$ | (Cond 1 OR Cond 2) AND Cond 3 |
| $3(011)$ | (Cond 1 AND Cond 2) OR Cond 3 |
| $4(100)$ | (Cond 1 OR Cond 3) AND Cond 2 |
| $5(101)$ | (Cond 1 AND Cond 3) OR Cond 2 |
| $6(110)$ | Cond 1 OR Cond 2 OR Cond 3 |
| $7(111)$ | Cond 1 AND Cond 2 AND Cond 3 |

## A.2. Ordinary Genetic Algorithms

The GA described below is a very basic version of a GA, and is referred to as the ordinary genetic algorithm (OGA). More precisely, it is very similar to the GA employed in Bauer (1994).

- The genetic algorithm maintains a population of individuals,

$$
\begin{equation*}
P_{i}=\left\{g_{1}^{i}, \ldots, g_{n}^{i}\right\} \tag{A.3}
\end{equation*}
$$

for iteration $i$, where $n$ is population size. Usually, $n$ is treated as fixed during the whole evolution. Clearly, $P_{i} \subset G$.

- Evaluation step: Each individual $g_{j}^{i}$ represents a trading strategy at the $i$ th iteration (population). It can be implemented with the historical data $r_{t-1}, r_{t-2}$, and $r_{t-3}$ by means of Eq. (2). A specific example is given in Eq. (3). Each trading strategy $g_{j}^{i}$ is evaluated by a fitness function, say Eq. (6).
- Selection step: Then, a new generation of population (iteration $i+1$ ) is formed by randomly selecting individuals from $P_{i}$ in accordance with a selection scheme, which, in this paper, is the roulette-wheel selection scheme.

$$
\begin{equation*}
M_{i}=P_{s}\left(P_{i}\right)=\left(s_{1}\left(P_{i}\right), s_{2}\left(P_{i}\right), \ldots, s_{n}\left(P_{i}\right)\right) \tag{A.4}
\end{equation*}
$$

where

$$
\begin{equation*}
s_{k}:\left\{\binom{G}{n}\right\} \rightarrow G \tag{A.5}
\end{equation*}
$$

$k=1,2, \ldots, n$, and $\left\{\binom{G}{n}\right\}$ is the set of all populations whose population size is $n$. The set $M_{i}$ is also called the mating pool.

- Alteration step: Some members of the new population undergo transformations by means of genetic operators to form new solutions.
- Crossover: We use two-point crossover $c_{k}$, which create new individuals by combining parts from two individuals.

$$
\begin{equation*}
O_{i}=P_{c}\left(M_{i}\right)=\left(c_{1}\left(M_{i}\right), c_{2}\left(M_{i}\right), \ldots, c_{n / 2}\left(M_{i}\right)\right) \tag{A.6}
\end{equation*}
$$

where

$$
\begin{equation*}
c_{k}:\left\{\binom{G}{n}\right\} \rightarrow G \times G, \tag{A.7}
\end{equation*}
$$

$k=1,2, \ldots, n / 2 . O_{i}$ is known as the set of offspring in the GA.

- Mutation: We use bit-by-bit mutation $m_{k}$, which creates new individuals by flipping, with a small probability, each bit of each individual of $O_{i}$.

$$
\begin{equation*}
P_{i+1}=P_{m}\left(O_{i}\right)=\left(m_{1}\left(O_{i}\right), m_{2}\left(O_{i}\right), \ldots, m_{n}\left(O_{i}\right)\right) \tag{A.8}
\end{equation*}
$$

where

$$
\begin{equation*}
m_{k}:\left\{\binom{G}{n}\right\} \rightarrow G \tag{A.9}
\end{equation*}
$$

$k=1,2, \ldots, n$.

- After the evaluation, selection and alteration steps, the new population $P_{i+1}$ is generated. Then we proceed with the three steps with $P_{i+1}$, and the loop goes over and over again until a termination criterion is met. The control parameters employed to run the OGA are given in Table A.3.

Table A.3. Control Parameters of OGA.

| Number of generations | 100 |
| :--- | :--- |
| Population size (n) | 100 |
| Selection scheme | Roulette-wheel |
| Fitness function | Accumulated returns |
| Elitist strategy | Yes |
| Rank min | 0.75 |
| Crossover style | Two-Point |
| Crossover rate | 0.6 |
| Mutation rate | 0.001 |


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